NCHRP 3-65: Applying Roundabouts in the United States

Design: Preliminary Findings

TRB Roundabout Conference, Vail, CO May 23, 2005



Bhagwant Persaud, Canada David Harkey, USA George Mason University, USA McDonald & Partners, UK Rensselaer Polytechnic University, USA Rod Troutbeck, Australia Ruhr-University Bochum, Germany University of Idaho, USA

- Design speed modeling
- Other design findings for motor vehicles
- Pedestrian and bicycle observations

- Karen Giese assisted in the speed analysis
- Ed Myers assisted in design review
- David Harkey led the ped/bike analysis

Current FHWA speed prediction method is based on AASHTO speed-radius function.



Design speed modeling: Vehicle path definitions

- V₀: approach path radius
- Through movements
 - > V1: entry path radius
 - > V2: circulating path radius
 - > V3: exit path radius
- Left turns
 - > V1L: entry path radius
 - > V4: circulating path radius
 - > V6: left turn path exit radius
- Right turns
 - > V5: entry path radius
 - > V5x: exit path radius



Design speed modeling: V4, Left-turn circulating speed (all sites)



Design speed modeling: Exit speed (all sites), unadjusted



distance is limiting factor

Proposed exit speed equation



where:

•
$$V_3$$
 = V_3 speed, in mpt

V_{3pbase}

• V₂

 a_{23}

- = V_3 speed predicted based on path radius, in mph
- = V_2 speed predicted based on path radius, in mph
- = acceleration along the length between the midpoint of V_2 path and the point of interest along V_3 path = **6.9 ft/s**²
- d_{23} = distance between midpoint of V_2 path and point of interest along V_3 path, in ft

Design speed modeling: Exit speed (all sites), adjusted



Design speed modeling: Entry speed (all sites), unadjusted



distance is limiting factor

Proposed entry speed equation



where:

•
$$V_1$$
 = V_1 speed, in mph

V_{1pbase}

• V₂

a₁₂

- V_1 speed predicted based on path radius, in mph
- = V_2 speed predicted based on path radius, in mph
- = deceleration between the point of interest along V_1 path and the midpoint of V_2 path = -4.2 ft/s²
- d_{12} = distance along the vehicle path between the point of interest along V_1 path and the midpoint of V_2 path, in ft

Design speed modeling: Entry speed (all sites), adjusted



Implications for design

- Tangential or nearly tangential exits do not appear to cause excessive vehicle exit speeds if the following conditions are met:
 - > The speed of circulation (V2 and V4) is kept low
 - The distance between the start of the exit path and the point of interest (e.g., crosswalk) is kept short
- Entry speed appears to be limited by drivers' anticipation of the speed needed for circulation
 - > However, recommend continued reliance on entry path curvature as a primary method to control entry speed

Additional findings regarding design and safety

- The single-lane sites included in the study have better crash frequencies and crash rates than the multilane sites in the study
- The majority of the multilane sites were designed before the concept of path overlap was included in any documentation (FHWA Roundabout Guide)

Additional findings regarding design and safety

- Narrow lane widths (entry and circulating) at multilane roundabouts appear to have a detrimental effect on safety
- Entry width:
 - > Aggregated entry width (number of lanes) has a clear safety and operational effect
 - > Variations of lane width appear to be second-order effects

Additional findings regarding design and safety

Angle between legs:

- > Found to be a significant effect in US data
- Solution As angle to next leg decreases, number of entrycirculating crashes increases

Splitter island width

> No strong effect between splitter island width and entry capacity found

- Apparent contributor to high crash frequencies at multilane roundabouts
- Anecdotal evidence suggests that its correction can substantially improve safety performance

Non-motorized Users

Examination of observed field behaviors for two groups:

- Pedestrians
- Bicyclists

Pedestrian data:

> 10 approaches at 7 sites; 769 events

Bicyclist data:

> 14 approaches at 7 sites; 690 events

Geographic diversity:

 California, Florida, Maryland, Nevada, Oregon, Utah, Vermont, Washington

How do motorists behave when encountering pedestrians?

Motorists failing to yield to pedestrians

- > All sites: 30 percent
- > Entry leg: 23 percent
- > Exit leg: 38 percent
- > 1-lane approaches: 17 percent
- > 2-lane approaches: 43 percent

Are there conflicts between motorists and pedestrians?

- Only 4 conflicts observed out of 769 pedestrian crossings (0.5%)
- Conflict rate: 2.3 conflicts per 1000 opportunities

How do behaviors at roundabouts compare to other forms of control?

Crossing control	Percent of "normal" crossings	Percent of non- yielding vehicles
Uncontrolled	70%	48%
Roundabout	85%	32%
Signal- controlled	90%	15%
Stop- controlled	100%	4%

No practical differences in walking speed

What are the roundabout characteristics that tend to cause problems or tend to be safer?

- Motorists less likely to yield on 2-lane approaches compared to 1-lane approaches
- Motorists less likely to yield on exit leg compared to entry leg
- Pedestrians more likely to hesitate when starting crossing from exit leg
- Review of geometric features did not yield additional insights

How do motorists and bicyclists interact?

Lane position on approach:

- > Edge of lane/bike lane: 73%
- Claim lane: 15%
- Sidewalk: 12%

Lane position on exit:

- Edge of lane: 61%
- Claim lane: 16%
- Sidewalk: 23%

Little observed interaction between modes

Bikes tended to wait for gaps in circulating traffic

Are there conflicts between motorists and bicyclists?

- Only 4 conflicts observed in 690 bicyclist events (0.5%)
- Small number of observed events of wrongway riding (7)

Conclusions

- Adjustments to speed model improve predictive ability
- Statistical and anecdotal evidence that various geometric factors influence safety
- Little observed safety problem for pedestrians and bicyclists, although some roundabout characteristics make use more challenging

Questions?

(503) 228-5230 or (800) 878-5230 Lrodegerdts@kittelson.com

