Roundabout Planning

22nd Century

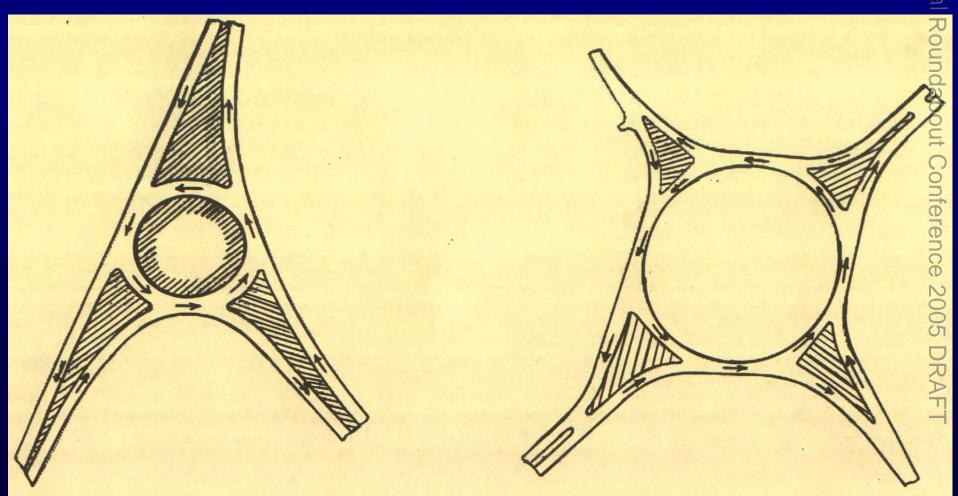
Prof. A. R. Kaub, BSCE, MSCE, Ph.D., P.E. Chantilly, VA

First things first - Open your mind

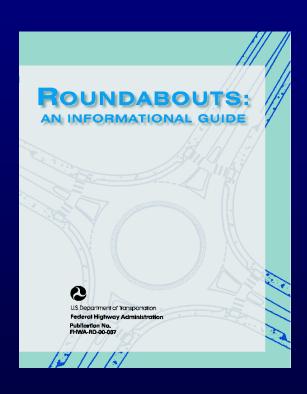


To achieve something new - Think outside of your experience

Background Traffic Circles/Rotaries



Today, we're fortunate to have a generalized guide that suggests



"The design problem is essentially one of determining a design that will accommodate the traffic demand while minimizing some combination of delay, crashes, and cost to all users, including motor vehicles, pedestrians, and bicyclists.

Generalized Categories of Roundabouts

Urban

Mini
Low Capacity
Moderate Capacity
High Capacity

,

Single entry lane

Double entry lanes

Rural

Moderate Capacity High Capacity

Single entry lane Double entry lanes

05 DRAFT

Generalized Design Features

						<u> </u>
Design Elements	Mini- Roundabout	Urban Compact	Urban Single-Lane	Urban Double-Lane	Rural Single-Lane	Rural Double-lane
Design Speed (mph)	15	15	20	25	25	30 Ound:
Entering Lanes per approach	1	1	1	2	1	2 dabout
Inscribed Circle Diameter (ft)	45 - 80	80 -100	100 -130	150 -180	115 -130	180 - 200nfe
Typical ADT 4-leg Roundabout (veh/day)	10,000	15,000	20,000	Chapter 4 (20-40,000+)	20,000	Chapter 45 (20-30,0004)

And from construction of these, generalized (after-the-fact) safety comparisons

Type of		Before	e Rounc	labout	Ro	undab	out	Percent change ⁵			
roundabout	Sites	Total	lnj. ³	PDO ⁴	Total	lnj.	PDO	Total	lnj.	PDO	
Small/ Moderate ¹	8	4.8	2.0	2.4	2.4	0.5	1.6	-51%	-73%	-32%	
Large ²	3	21.5	5.8	15.7	15.3	4.0	11.3	-29%	-31%	-10%	
Total	11	9.3	3.0	6.0	5.9	1.5	4.2	-37%	-51%	-29%	

Have all of these been built with an accurate expectation of the result?

Well we hope so but, action without accurately estimating the result can be VERY expensive.



In Roundabout Planning, many elements need identification and definition before a reasonable decision can be reached.

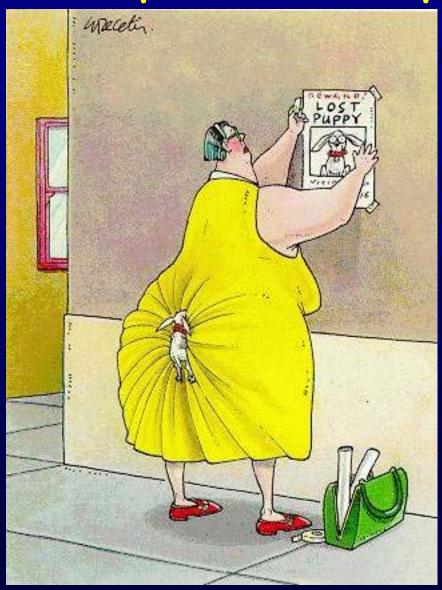
- Traffic operations benefits (but delay of marginal value)
- Safety benefits (Nominal Safety versus Substantive Safety)
- Maintenance savings (save signal equipment & energy)
- Environmental enhancement (less stops, emissions & noise)
- R.O.W. saving (more intersection area but less queue storage)
- Traffic calming / aesthetics / older drivers (marginal value?)
- Pedestrian / bicycle operation & safety
- Desirable roundabout planning goal ?

_"The roundabout problem is essentially one of determining a design that will accommodate the traffic demand while <u>minimizing some combination of delay,</u> <u>crashes, and cost to all users</u>" (FHWA Roundabout Guide) compared to other intersection traffic control types such as TWSC, AWSC or multi-phase signalized.

But HOW do you do that?

Let's begin with understanding MACRO and MICRO

Macroscopic vs Microscopic



Or NOMINAL (Macroscopic) versus Substantive (Microscopic)

EXAMPLE

MACROscopic or **NOMINAL** Planning Model **Highway Capacity Software**

(Regression Models about 50-70% accurate compared to field data)

or

MICROscopic or SUBSTANTIVE Planning Model Netsim / Corsim

- about 75% accurate compared to field data
- vehicle to vehicle interactions

MACROscopic Roundabout Delay Model

(pg. 93 - FHWA Guide)

Delay =
$$\frac{3600}{c_{m,x}}$$
 + 900 T $\left(\frac{v_{x}-1}{v_{x-1}}\right)^{2}$ + $\left(\frac{3600}{c_{m,x}}\right)\left(\frac{v_{x}c_{m,x}}{v_{x}c_{m,x}}\right)$ + 5

Where:

delay = average control delay (sec/veh)

V_x = flow rate for movement x (veh/hr)

c_{mx} = capacity of movement x (veh/hr)

T = analysis time (hour)

And:

V_x / c_{mx} = from HCM Roundabout analysis (pg. 17-45 & 17-99 (2000 HCM)

HCM ROUNDABOUT DELAY & LOS Software

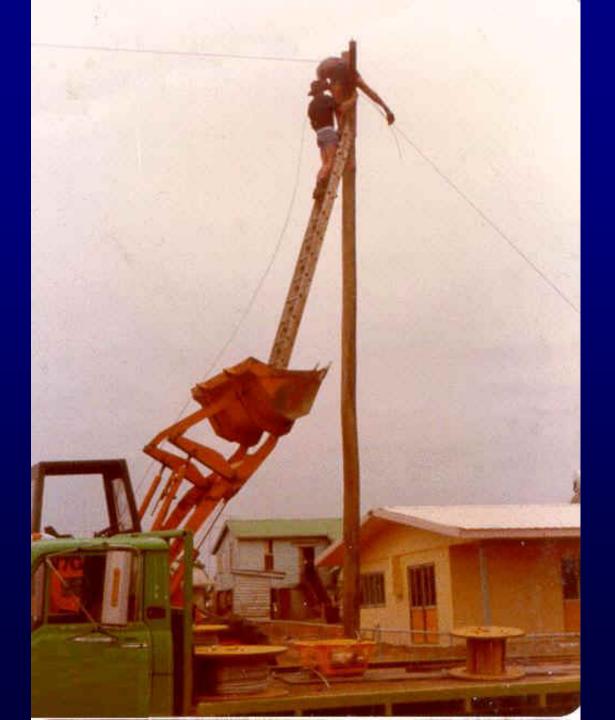
												=
2000 HCM ROUNDABOUT CONTROL	EB		NB		WB		SB					
LT FLOW RATE	Analysis :	Period =	0.25	V1	247	V7	143	V4	103	V10	254	
THROUGH FLOW RATE		Upper	Lower	V2	308	V8	207	V5	393	V11	94	2
RT FLOW RATE	Critical gap =	4.1	4.6	V3	105	V9	77	V6	123	V12	152	_
Effective LANES ON SUBJECT APPRO	Follow-up =	4.1	4.6		1		1		1		1	2
APPROACH FLOW RATE/lane	(For TS - Assum	e Follow	-up=Critical	l gap)	660		427		619		500	
					V4+V10+V11		V1+V2+V10		V1+V7+V8		V4+V5+V7	2
CIRCULATING FLOW RATE/lane	451		809		597		639	-				
UPPER BOUND	672		535		613		597					
LOWER BOUND		579		447		522		506				
CAPACITY/LANE UPPER					672		535		613		597	2
CAPACITY/LANE LOWER		579		447		522		506				
V/C RATIO UPPER		0.98		0.80		1.01		0.84	-			
V/C RATIO LOWER		1.14		0.96		1.19		0.99	Ç			
APPROACH CONTROL DELAY (2000)	107.6		62.9		127.7		65.7	1				
APPROACH LOS (2000 HCM) =					F		F		F		F	
HCM Compatible Roundabout Delay =	INDAB	OUT LOS =		HCM LOS	'F'				C			

While some think reduced delay = reduced accidents, often "what seems to be....just isn't"



Let's look at some situations that may not appear "Safe" Are they?











And the winner ...is...... (welding on the gas tank)



Safety Levels of Service Never Adopted by Engineering Profession Why Not?

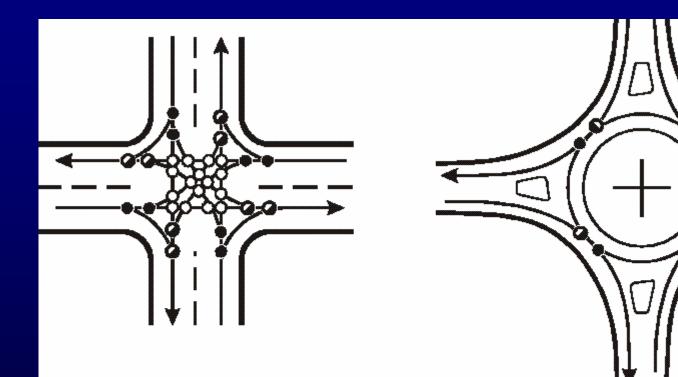
Prior research says - Government has a Conflict of Interest because the Government entity that designs highways can't also admit to their being unsafe.

THUS:

Over Last 25 years - Engineering Profession created the HCM and often assumed Delay as a safety surrogate

OR create "Apparent Safety Models"
(variables are so macro, that the standard deviation is excessive making the models grossly unreliable predictors)

MACROscopic Nominal Safety Model Comparison of Vehicular Conflict Points



- Merging 8
- Diverging 8
- O Crossing 16 32



- Diverging
- O Crossing 0

MACROscopic Nominal Safety Model

Injury + Fatal Accidents/yr at Urban 4-leg Signalized

(FHWA-RD-99-094)

	A	С	D								
1	Multiple Linear Regression Model										
2	Injury and Fatal Crashes Urban 4-Leg Signalized Intersections										
3		25,000	•								
4		ADT Minor	20,000								
5		Design Speed	50								
6	Variable	Variable Level	Coefficient	Value							
7	Intercept		-5.745	1							
8	ADT Major		0.574	1							
9	ADT Minor		0.215	1							
10	Signal Timing	Pretimed	-0.051	0							
11		Semi-actuated	0	0							
12		Fully actuated	0.4	1							
13	Signal Phasing	Two-phase	0	0							
14		Multiphase	-0.24	1							
15	Access Control on Major	None	-0.29	1							
16		Partial	0	0							
17	Design Speed on Major (mph)		0.005	50							
18	Number of Lanes on Minor	3 or less	-0.155	0							
19		4 or more	0	1							
20	Number of Lanes on Major	3 or less	-0.163	0							
21		4 or 5	-0.151	0							
22		6 or more	0	1							

ISSUES:

- 1. INDIVIDUAL VEHICLES? NO
- 2. WHAT IF ALL VEHICLES TURN LEFT? Same RESULT
- 3. DESIGN SPEED or POSTED SPEED?
- 4. DATA COLLECTION RADII = 250 ft. (Excluded rear-end events in long queues)

Even the BEST FHWA accident models only produced predictions with about 35% accuracy.

MACROscopic Nominal Safety Model British Roundabout

1	A	В	С	D	Е	F	G	Н	I	J	K	L	
2	Injury and Fatal Accid	ents at R	ounda	bouts	;		ADT	45,000				0110	
3													ש
4	Flow (Left, Through, Right) (%)	0.10	0.80	0.10			ADT minor/ADT Total	0.44					Į,
5							ADT Major	25,000					
6							ADT Minor	20,000					D
7	Roundabout Characteristics					,						2	2
8		Major	Minor	Major	Minor								
9	Approach	1	2	3	4		Approach	1	2	3	4	כר	
10	e (m) - entry width	11	11	11	11		Qe (entering flow)	12,500	10,000	12,500	10,000		
11	v (m) - approach width	8	8	8	8		Qc (circulating flow)	10,250	12,250	10,250	12,250		2
12	Di (m) - inscribed circle diameter	60	60	60	60		Q exiting flow	12,000	10,500	12,000	10,500	=	
13	Dc (m) - central island diameter	40	40	40	40)
14	Ra (m) - approach radius	300.00	300.00	300.00	300.00								D
15	Re (m) - entry radius	70.00	70.00	70.00	70.00		Approach	1	2	3	4		5
16	Pm (%) - proportion motorcycles	0.01	0.01	0.01	0.01		Accident Type					Total by Type	ע
17	Q (degrees) - angle between arms	90.00	90.00	90.00	90.00		Entry - Circulating	0.22	0.20	0.22	0.20	0.83	
18	Pedestrians/day	0	0	0	0		Approaching	0.18	0.13	0.18	0.13	0.62	
19	ev - approach width correction	88	88	88	88		Single Vehicle	0.29	0.25	0.29	0.25	1.08	_
20	R - (Di / Dc)	1.50	1.50	1.50	1.50		Other	0.13	0.12	0.13	0.12	0.50	_
21	Ca - approach curvature	0.00	0.00	0.00	0.00		Pedestrian	0.00	0.00	0.00	0.00	0.00	
22	RF - ratio factor	0.73	0.73	0.73	0.73		Total for Approach	0.82	0.69	0.82	0.69	3.03	1
23	Ce - entry path curvature	0.01	0.01	0.01	0.01							_	
							ROUNDABOUT FAT	3.03					

BUT, why isn't speed a factor in injury prediction?

Alternative Nominal Macro-models

(Not sensitive to significant variables)

- 1. Maryland DOT
 - a. Annual accidents = 1.53 / mev
 - b. Annual injury accidents = 0.11 / mev
- 2. Other Roundabout Software
 - a. Delay based on HCM
- b. Linear regression accident models

 Crashes/Yr = 1.64 x10⁻¹² * ADT 1-way 1.17 * Posted Speed 4.12 * Length

Vehicle Path Radius 1.91

These never mention accuracy of the accident models – accuracy is assumed

......that's like selecting an open-heart surgeon without checking references.......
Smart?......Good Planning?......



"Nurse, get on the internet, go to SURGERY.COM, scroll down and click on the 'Are you totally lost?' icon."

Who picked this surgeon?.....I did????

Proper Roundabout Planning – the goal

- Develop preliminary design (Urban-low trucks/low entry speeds or Rural)
- Determine if right-of-way available
- Examine planning steps
 - Think GLOBALLY Regional considerations
 - Think LOCALLY Substantive Operations
 - Single / Dual lane ?
 - Speed?
 - Geometry Inscribed diameter / central island diameter / bypass lane ?
 - Define SUBSTANTIVE (microscopic) SAFETY elements & value
 - Define NOMINAL (macroscopic) DELAY elements & value
 - Combine SAFETY + DELAY Values (\$) to estimate annual performance
 - Compare to Alternate Traffic Control Strategies
- Estimate Potential Safety of Proposed Design (Safety LOS)

Roundabout DELAY Analysis for planning purposes

In planning studies the value of delay is highly variable and is often excluded in the B/C ratio, thus a Macroscopic model like the HCM is generally used to minimize data input needs and the cost of analysis.

Highway Capacity Manual – 2000

with the worst-case assumptions of:

- 1. Critical gap = 4.6 seconds similar to Rt. Turn "Yield" of 1985 HCM (5.0 sec), and conforms to 2003 roundabout gap research (4.2 sec at 50% acceptance).
- 2. No Follow-up time since each driver must make independent gap selection.
- 3. Delay is a consistent user-defined \$-value over all scenarios

But what about safety?

Roundabout SAFETY ANALYSIS

In planning studies the value of safety is entirely dependent on the predicted number and cost of injuries assuming that fatalities are rare & unpredictable events and that fender-bender (pdo) events are an economic benefit that creates jobs and have no negative value, thus the use of a MICROscopic accident prediction model to define injury accidents is ESSENTIAL.

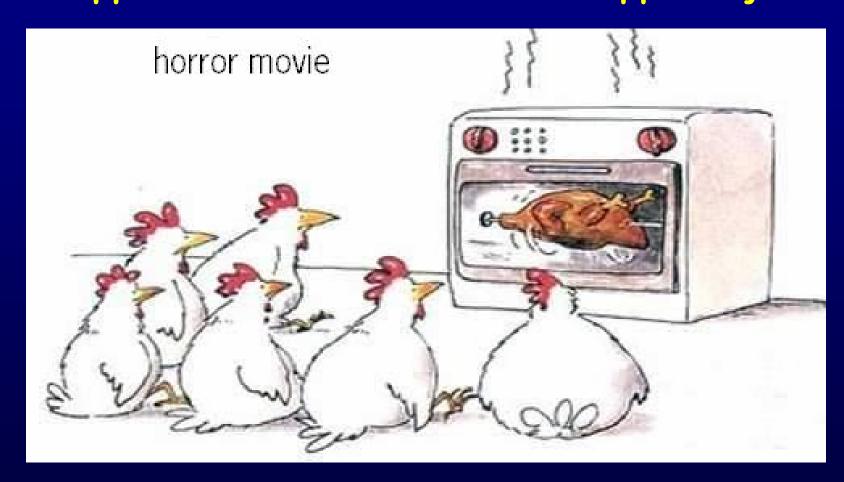
But let's also assume:

If the risk of injury is <u>not unacceptable</u>, thus crashes, injuries (and even unlucky fatal injuries) are expected but undesirable by-products of mobility, and thus some Un-safe events <u>ARE undesirable but acceptable</u>.

The problem is: How do you define "some" or how many unsafe events?

But first – let's talk about MICROscopic accident prediction and then we'll define SAFE versus UNSAFE!

To begin, the one thing you do know about safety is that....if it happened to others...it could well happen to you.



So, rather than waiting for accidents and death to happen & then correct them with "safety programs" which are nothing but lists of failures, we have new technology to help us be pro-active in traffic safety using.....

Traffic Conflicts as a surrogate for predicting accidents:

- 1. NOT Tail light braking conflict studies
 - 2. NOT Conflict Point comparisons
- 3. YES Theoretical "Opportunities for Conflict"

Tail-light braking conflicts

FACT

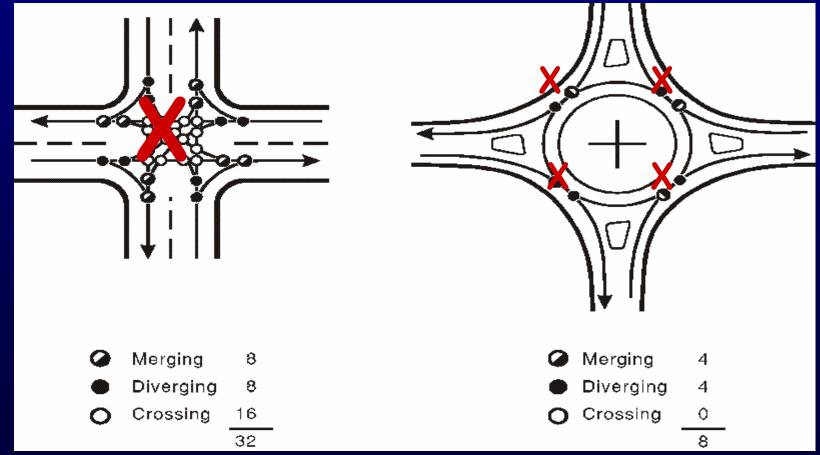
Actual application of Taillight braking was never found to be consistently correlated to accidents



Conflict Point Comparisons

FACT

Conflict Points are correlated to accident potential but the dynamics are very complex



For Planning Purposes Define Roundabout Safety Benefits with

MICROscopic Sunstantive Model based on individual vehicle conflict-opportunities

(Traffic Safety Software @www.TRAF-Safe.com)

Assumptions for conservative analysis:

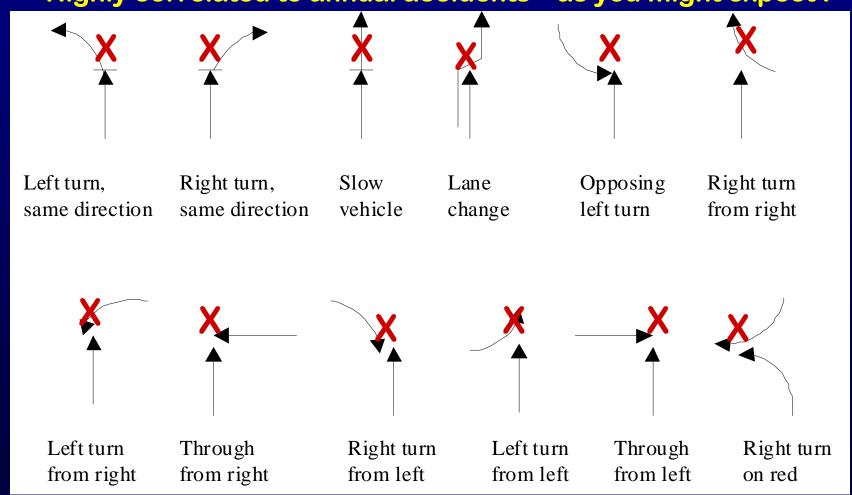
- 1. Fatal events are not estimated or valued but are added to injury accidents
- 2. Injury and vehicle damage are consistent user-defined \$values.

What is a Conflict Opportunity?

An actual occurrence in which 2 or more vehicles or users approach one another such that there is a theoretical probability of collision assuming unchanged trajectories.

Theoretical Opportunities for Conflict

FACT
Highly correlated to annual accidents – as you might expect!



University of Virginia/VDOT VTRC Report 04-R11

"Development of Left Turn Lane Guidelines"

March 2004

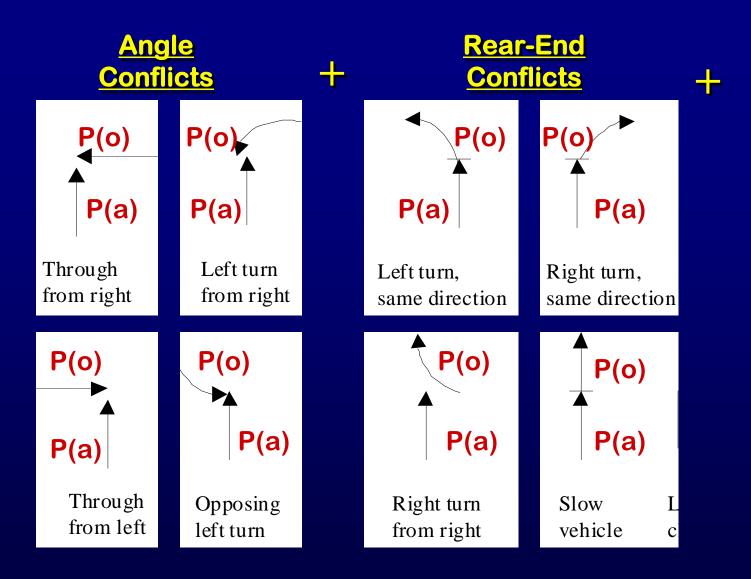
Recommendations

"The safety surrogate measure used in this study was solely based on conflict opportunities."

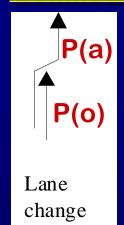
"Future research should quantify the extent to which conflict opportunities can predict crashes such that the impact of safety can be better incorporated ..." (pg. 46)

Conflict Opportunity Accident Research

- 1. <u>"Predicting Annual Intersection Accidents with Conflict Opportunities"</u> presented to TRB, Washington, D.C., January, 2001 and published in the proceedings of the AASHTO/ITE/TRB Urban Street Symposium; A.R. Kaub & K.M. Taylor, Dallas, Texas; June, 1999 www.nationalacademies.org/trb/publications/ec019/ec019.pdf
- 2. <u>"A Corridor Road Safety Audit with Safety Software"</u>
 presented to TRB, Washington, D.C., January 2000 and published in the proceedings of the ITE Conference New Tools for Enhancing Transportation Safety in the 21st Century, A.R. Kaub & J.A. Kaub, Orlando, Fl., 1999.
- 3. <u>"Predicting Annual Intersection Accidents with Conflict Opportunities"</u>, presentations to University of Virginia Civil Engineering / VTRC / VDOT planning staffs, A.R. Kaub, 1995-1999.
- 4. <u>"Validation of a Conflict Opportunity Intersection Accident Prediction Model"</u> presented to TRB, Washington, D.C., 1998 and published in the proceedings of the TRB 2nd Access Management Conference; A. R. Kaub, Vail, Colorado; 1996.
- 5. "Validation of the Probable Conflict Opportunity Accident Software for Two-way Stop Control Intersections", Florida DOT Research Contract # B9212, A.R. Kaub, 1996.
- 6. "Managing Highway Access with Conflict Opportunity Crash Prediction Software" A.R. Kaub, presented to the USDOT, FHWA/Turner-Fairbank Safety Research, 1993.
- 7. "Design Guide for Auxiliary Passing Lanes on Rural Two-Lane Highways using Conflict Opportunity Accident Estimation", A.R. Kaub & W.D. Berg, TRR 1195, 1987.



Sideswipe Conflicts



Fixed Object / Single Vehicle Events

What is Conflict Opportunity Technology?

Originally Based on 1968
General Motors Conflict Opportunity Research

by Perkins & Harris

Angle Accidents = f(Angle Conflict Opportunities)

Rear-End Accidents = f(Rear-end Conflict Opportunities)

Sideswipe Accidents = f(Sideswipe Conflict Opportunities)

Fixed Object/Single Vehicle Accidents = f(FO/SV Conflict Opportunities)

But
GM couldn't integrate these into Total Annual Accidents

Today's Conflict Opportunity Technology does what GM couldn't do

Assumptions

- Typical Drivers, Vehicles, Environment, Profile, Adequate SD
- 4 Conflict Types- Angle, Rear-end, Sideswipe, Single Vehicle

Common Poisson Conflict Opportunity Forms

$$P(Arrival) = e^{-mean \ arrival \ flow \ rate}$$
 & $P(Opposition) = e^{-mean \ opposing \ flow \ rate}$

(Arrival Exposure Time)

Probability of Conflict (angle, rear, side, single) = $P(Arrival) \times P(Opposition)$

Annual Summation of Independent Conflict Types

```
Annual Conflict Opportunities = ± a (<u>P-Angle CO</u>) ± b (<u>P-Rear end CO</u>)

± c (<u>P-Sideswipe CO</u>) ± d (<u>P-Single Vehicle</u>)
```

a,b,c,d = Speed-based coefficients calibrated to National Accident Data using the drivers <u>visual perceptive capability</u> for each type of conflict

Convert Annual Probable Conflict Opportunities to Annual Accidents

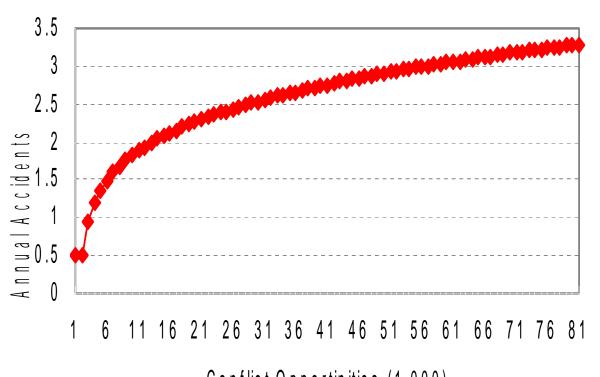
Annual Accidents = <u>Total Annual Conflict Opportunities</u> Conflict Opportunity/Accident Ratio

Conflict Opportunity = Family of Curves calibrated to

Accident Ratio speed, geometry, volume for each type of traffic control device

Example Annual Conflict Opportunity/Accident Ratio

(One of a Family of Volume, Geometry, and Speed, Dependent Curves)



Conflict Opportinities (1,000)

At low volumes, it takes
few opportunities for
conflict to generate one
accident, but at higher
volumes it takes
exponentially increasing
opportunities to generate
that same accident.

That's because as volume increases, both reduced speeds and car-following aid the drivers visual perception to generate safer operation over all accident types.

Finite Element Analysis

Finite Element Analysis Finite Element Analysis

Finite Element Analysis

Finite Element Analysis

Finite Element Analysis

Time Finite Element Analysis

Lane Finite Element Analysis

Approach Finite Element Analysis

Traffic Control Finite Element Analysis

Intersection Finite Element Analysis

Corridor Finite Element Analysis

New Accident & Injury Prediction Technology

Inputs

Traffic Control selection (TWSC, AWSC, Signal or Roundabout)

Peak Hour Am and Pm volume by lane with other hours interpolated

Approach geometry & turn bay length

Approach speeds & turning radii

Numerous HCM-based vehicle & flow variables

Actuated Signals (each hour of day)

Automatic - Cycle length and phase selection

Automatic - Through and turn phase duration

Automatic - Hourly timing plans using sophisticated ICU

Almost 150 HCM Compatible INPUTS

Outputs

Hourly and Annual Delay

Hourly & Annual Accidents
Injury-based Safety Levels of Service & Lifetime Risk of Injury
&

Performance Index

∑ Utility (\$Delay/yr + \$Injury accidents/yr)

Planning and Design Goal:

If the traffic control type selection is "Safe", then minimize Performance Index (minimum delay and injury values) and over all "Safe" types of traffic control devices.

So Unique - US Patent # 6,662,191

United States Patent.

6,662,141

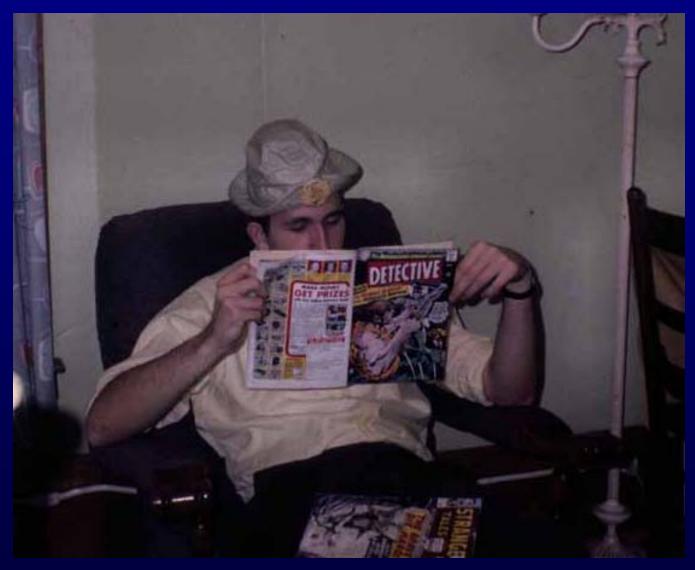
December 9, 2003

Traffic safety prediction model

Abstract.

A Traffic Safety prediction Computer Program (TRAF-SAFE) and sub-models for predicting the number of accidents, injuries and fatalities expected annually at an intersection or series of intersections based on the particular intersection and roadway features. A finite analysis approach to an intersection is used to break the intersection into discrete elements such as lanes, tumbays, stop control signals, and traffic flow rates. The total annual expected accidents can then be calculated as a summation of the interrelation of the individual elements. A Poisson's distribution is used to statistically estimate the likelihood of the individual vehicles occurring within a discrete time frame being investigated. The conflict probabilities between various permutations of the traffic flow is then calculated and summed to determine the number of conflicts for the intersection or roadway. The conflicts are then converted to expected accidents, and the accident level is converted to injury involvements and Safety Levels of Service for the intersection and roadway.

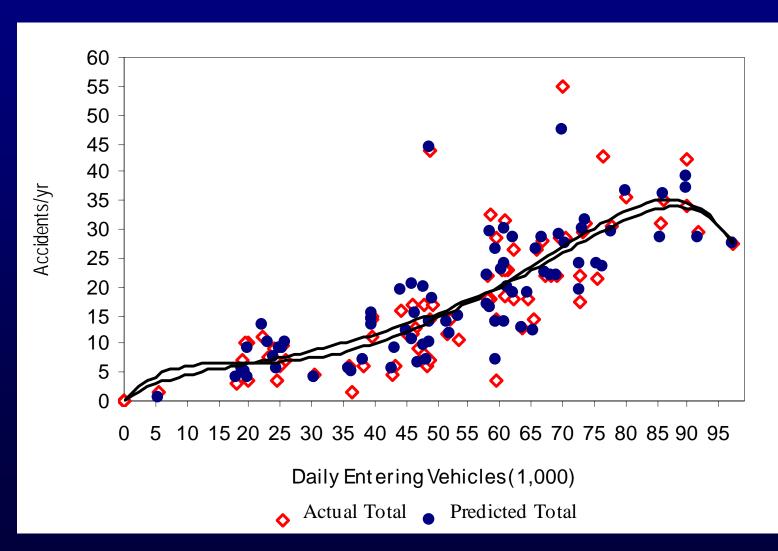
Ya, sure I read all about it...



...but how do I know it works?

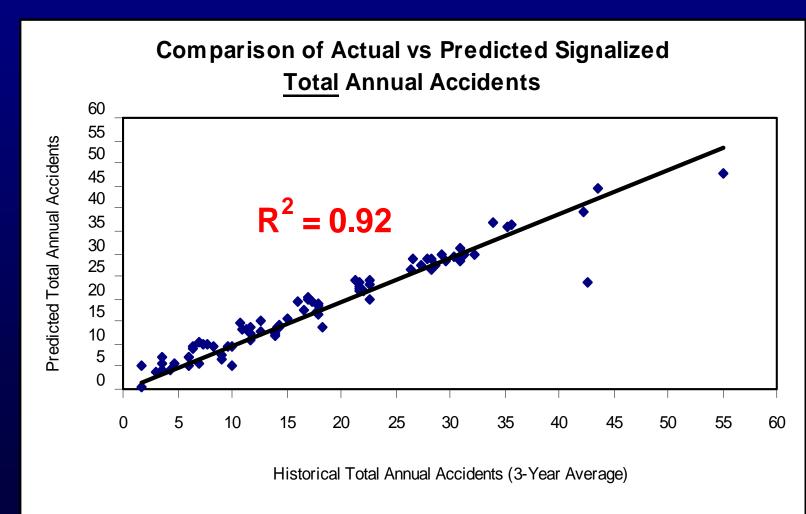
Signals Total Accidents/yr

(Northern Virginia Actual Site Data and Accident History)



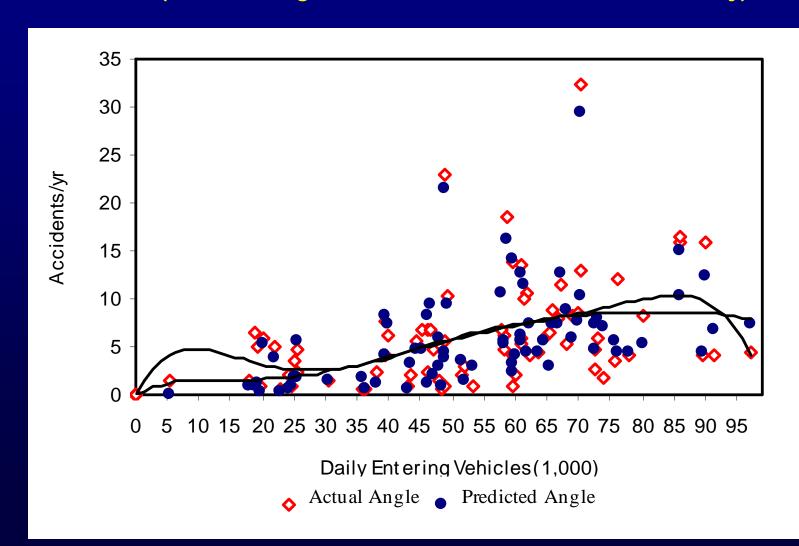
Signals Total Accident Validation

(Data From 100 Signalized Intersections in Northern Virginia)



Signals Angle Accidents/yr

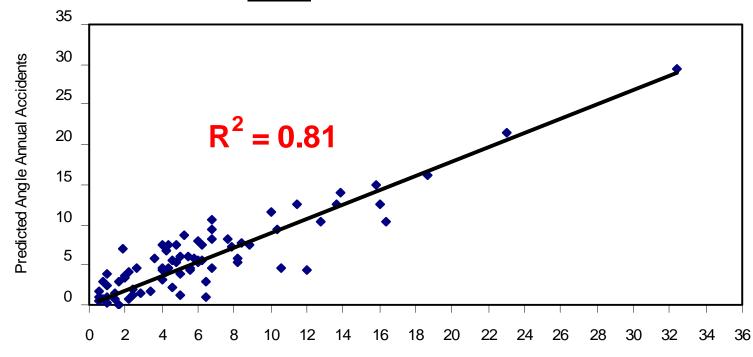
(Northern Virginia Actual Site Data and Accident History)



Signals Angle Accident Validation

(Northern Virginia Actual Site Data and Accident History)

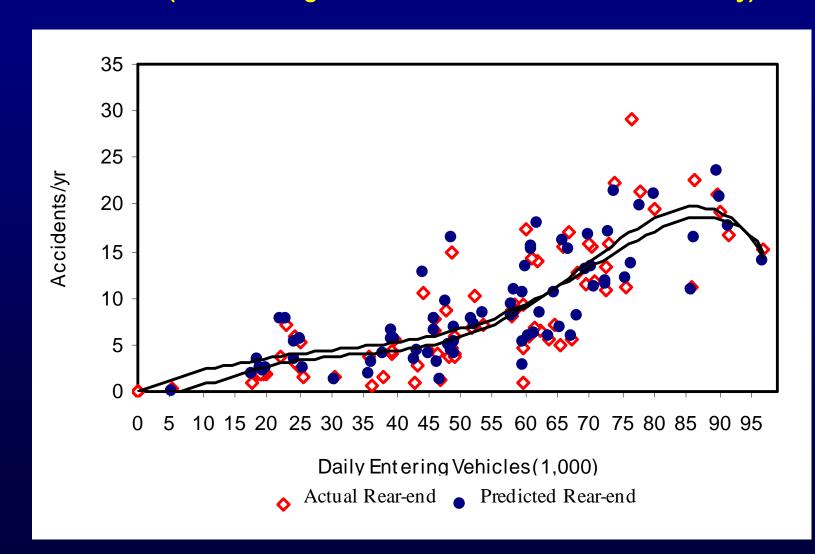
Comparison of Actual vs Predicted Signalized <u>Angle</u> Annual Accidents



Historical Total Annual Accidents (5-Year Average)

Signals Rear-End Accidents/yr

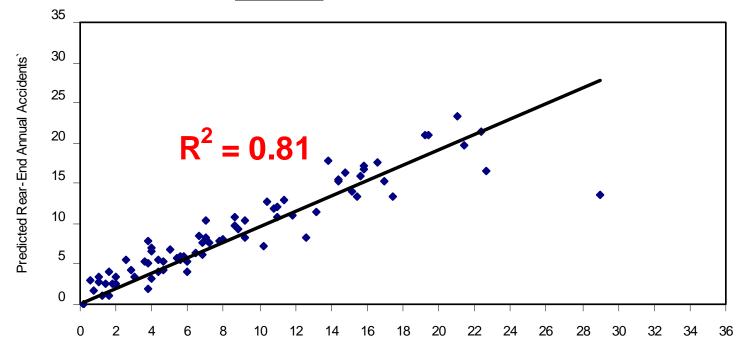
(Northern Virginia Actual Site Data and Accident History)



Signals Rear-End Accident Validation

(Northern Virginia Actual Site Data and Accident History)

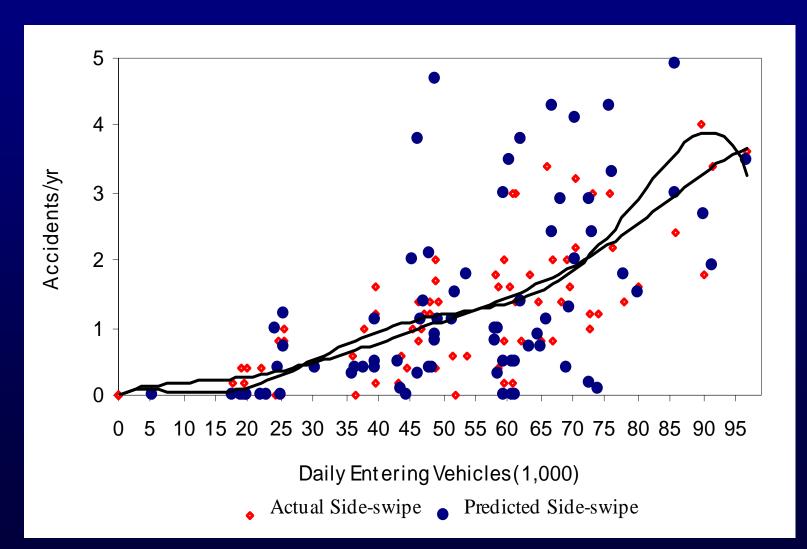




Historical Rear-End Annual Accidents (5-Year Average)

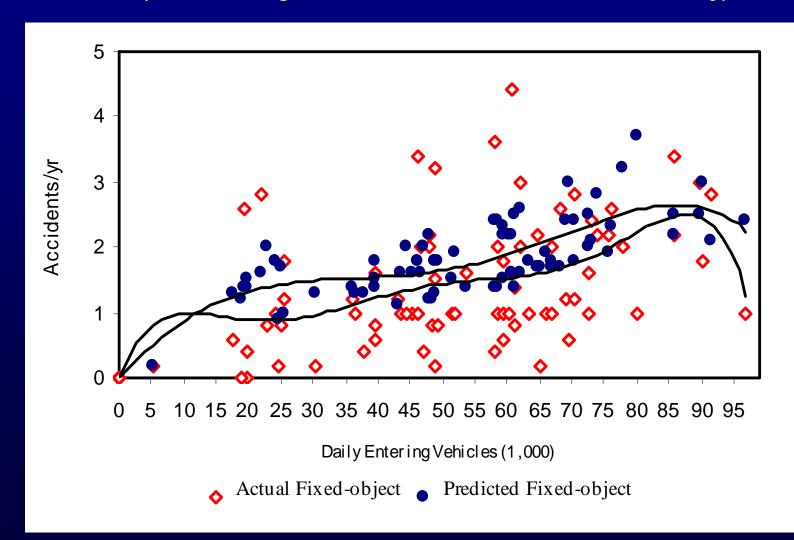
Signals Sideswipe Accidents/yr

(Northern Virginia Actual Site Data and Accident History)



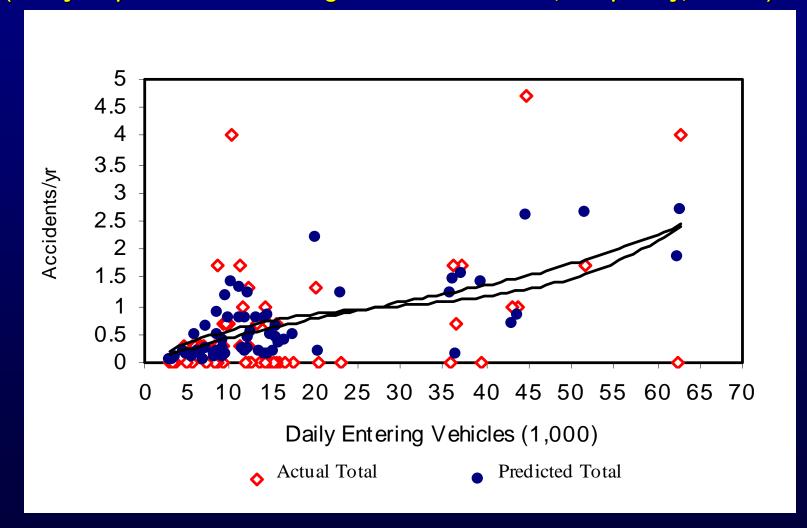
Signals Fixed Object/Single Vehicle Accidents/yr

(Northern Virginia Actual Site Data and Accident History)



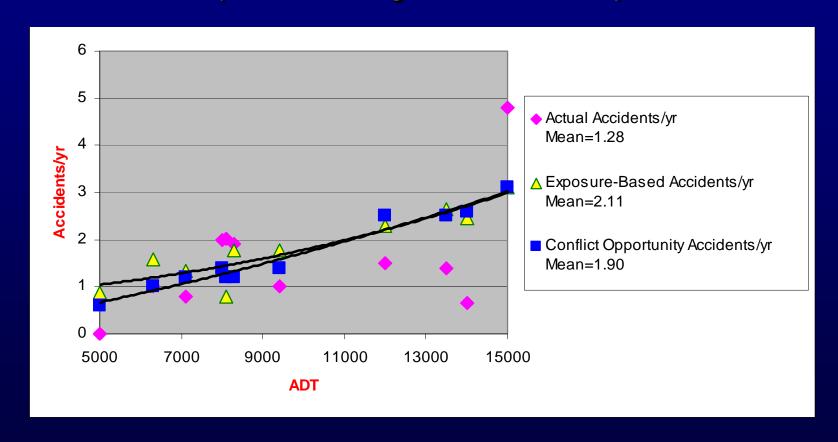
Unsignalized TWSC Total Accident Validation

(2-Way Stop Data From 65 Unsignalized Intersections, Tampa Bay, Florida)



Single Lane Roundabout Actual vs MDOT vs Conflict Opportunity

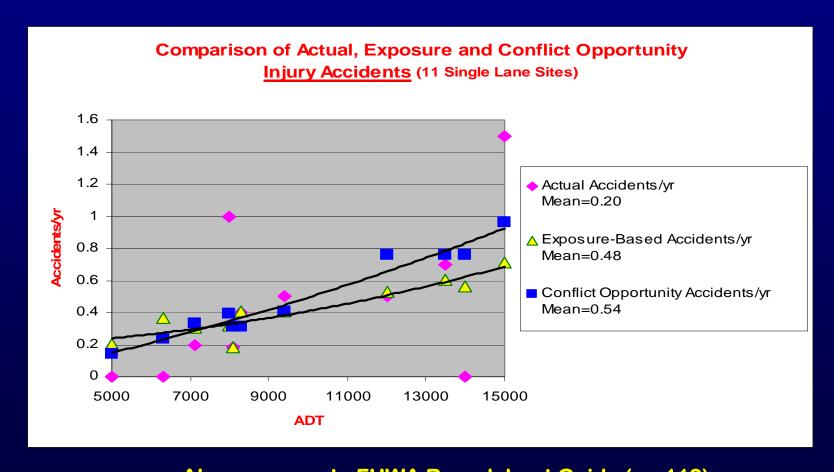
(for 11-MDOT single lane Roundabouts)



Also compare to FHWA Roundabout Guide (pg 112): Average Single-Lane Roundabout = 2.4 Accidents/yr

Roundabout Injury Accident Validation

(for 11-MDOT Roundabouts)



Also compare to FHWA Roundabout Guide (pg 112): Average Single-Lane Roundabout = 0.5 Injury Accidents/yr

National Roundabout Conference DRAFT

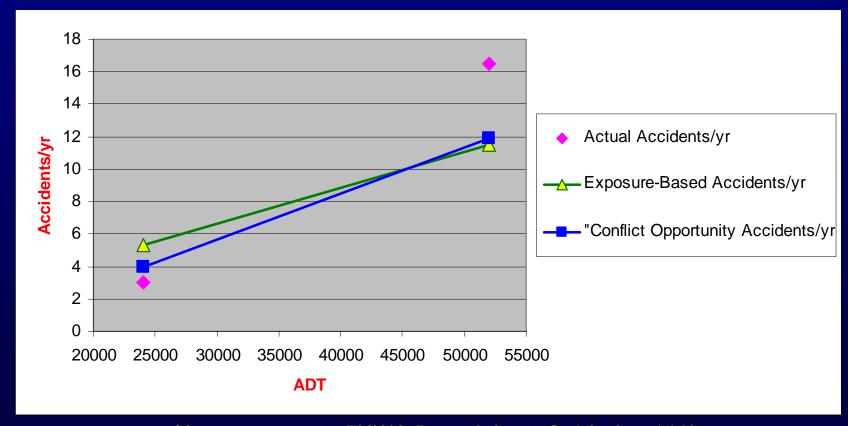
Roundabout Accident Type Validation

(for 11-MDOT Single lane Roundabouts)

Percentage Event Type	Conflict Opportunity Average from MDOT Data	Australia	Germany	Switzerland
Within Roundabout	55 (includes sideswipes)	51	30	46
Rear-End	15	18	28	13
S <u>ideswipe</u>	0	4 (within roundabou	O	0
Single vehicle/ Fixed Object	30	18	17	35

Dual Roundabout Accident Validation

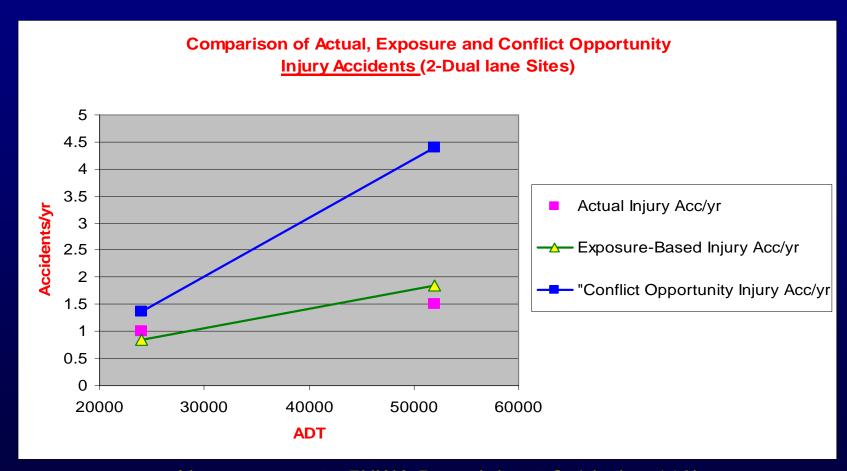
(for 2-MDOT Roundabouts)



Also compare to FHWA Roundabout Guide (pg 112): Average Dual-Lane Roundabout = 15.3 Accidents/yr

Dual Roundabout Injury Accident Validation

(for 2-MDOT Roundabouts)



Also compare to FHWA Roundabout Guide (pg 112): Average Dual-Lane Roundabout = 4.0 Injury Accidents/yr

In General

Conflict Opportunity Annual Accident Forecasts

1. Signalized Intersections -

- Over 80% accuracy (<1 STD) for 100 signalized intersections
- Angle & Rear-End Predictions within 15-20 percent of historical
- Total Accident Predictions within 10-15 percent of historical

2. Unsignalized Intersections (TWSC)

- Over 70% accuracy for 100 TWSC intersections

3. Roundabouts

- Over 80% accuracy compared to MDOT/FHWA averages

4. Overall -

Conflict Opportunity Technology offers annual accident estimates that are BETTER than ANY existing technology.

<u>Transportation Research Record 1111 (Berg & Ha - 1995)</u>

"The use of Opportunity-based accident measures will yield significantly different hazard rankings compared to conventional accident-rate expressions."

Well ok it works, but what seems like a "good idea" isn't necessarily a "safe idea"



So, how do you define something as "safe"?

SAFE or UNSAFE?

Intersection Safety LOS

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Quantity Thresholds (Upgrade Traffic Control Type from ITE)
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DRIVEWAY > 1 in 3 Years (< 0.33/ Year)

YIELD > 2 in 3 Years (< 0.66/ Year)

2-Way STOP > 5 in 1 Year (MUTCD)

ALL-WAY/SIGNALS??

Quality or Severity Thresholds

Injury-based Theoretical Guidance where

Lifetime Risk of Disabling Injury should be < 1.0, thus where

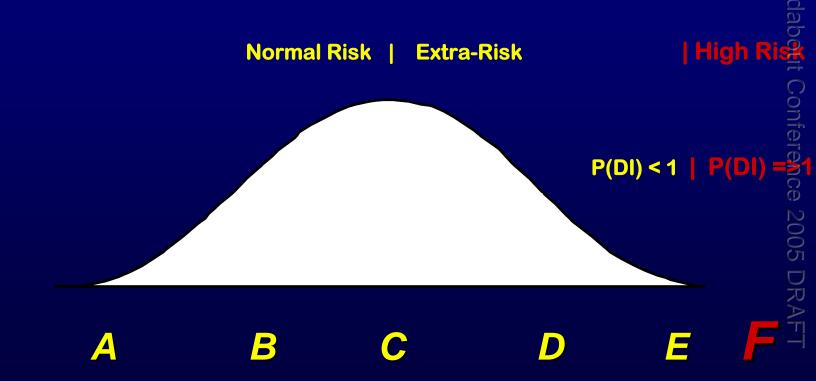
Probability < 1.0 Normal or Extra-Risk Levels (Safety LOS A-E)

Probability > 1.0 High-Risk of Disabling Injury (Safety LOS F)

Intersection Severity Levels of Service

Probability of Disabling Auto Injury per Lifetime

(assume driving risk is normally distributed throughout lifetime)



How to Define Safety LOS E/F Threshold

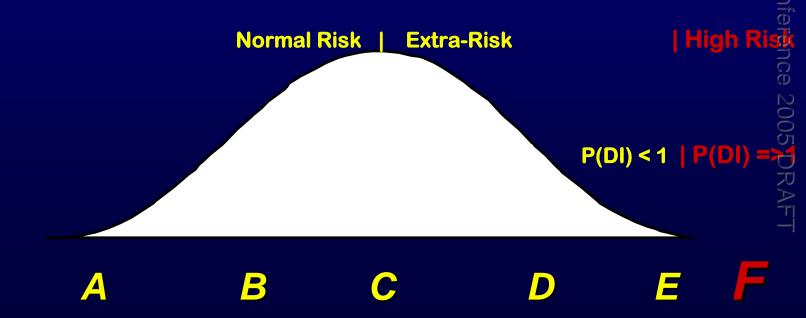
OSHA Standard Risk Threshold

The lifetime risk of death in any occupation should be less than 1 death in 1000 events

Using this guide, Ossenbruggen's FHWA analysis:

To achieve no more than 1 fatal accident in 1000 accidents, the number of injury accidents per year (which require professional treatment) should be less than about 7.8 / 10,000 ADT (entering an intersection).

("A Method of Identifying Hazardous Highway Locations using the Principle of Individual Lifetime Risk" by P.J. Ossenbruggen in Risk, Health, Safety & Environment, 1998, pg. 90 and funded by FHWA)

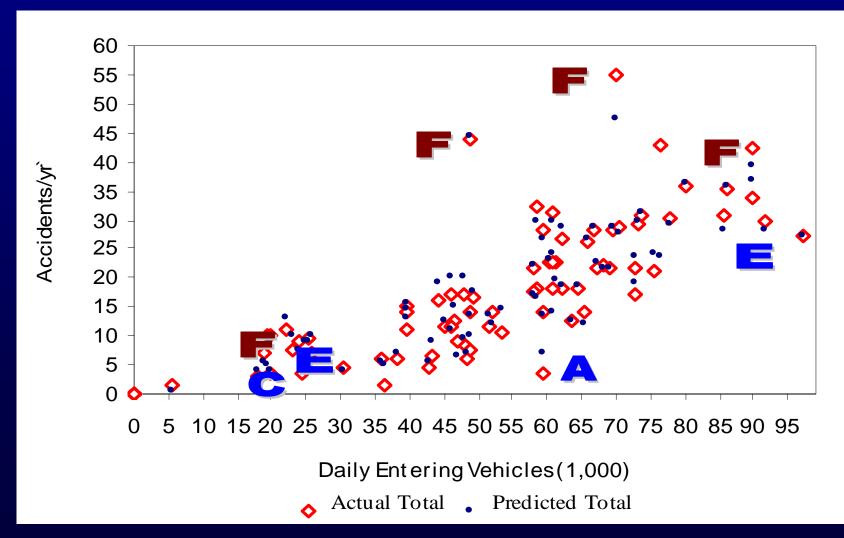


Define Safety LOS Example

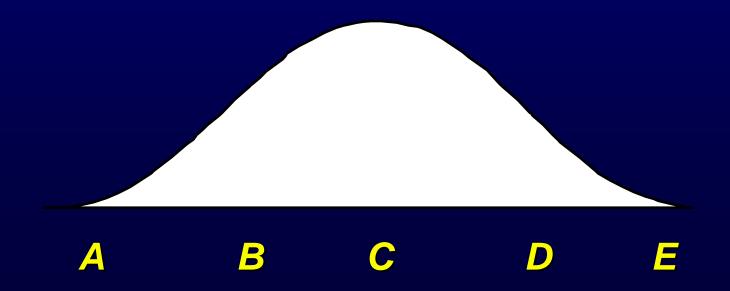
7.8 Maximum Annual Injury accidents / 10,000 ADT (entering any intersection) where 25% of all injury accidents occur at signal control 5% of all injury accidents at stop control 70% on all injury accidents at uncontrolled intersections/driveways thus Maximum Signalized Injury Threshold = 0.25 * 7.8 = < 2.0 Injury accidents-yr/10,000 ADT **Maximum Roundabout Injury Threshold = 50% of Signalized threshold (estimate)** Maximum Stop Control Injury Threshold = 20% of Signalized threshold = 0.05 * 7.8 = < 0.40 Injury accidents-yr/10,000AD thus for an urban 4-leg Stop control Intersection with 24,495 ADT the Maximum Injury accidents < 24,495 * 0.40 = < 0.98 IA/yr10.000 | High Risk Normal Risk | Extra-Risk $IA < 0.98 \mid IA > 0.98 \mid$

Intersection Injury-based Safety Levels of Service

(Northern Virginia Data)



Safe or Unsafe? Only Defined by Professionally Qualified Engineering Judgment



But what if the Safety LOS = F?

1. Warn the driver – MUTCD



- 2. Begin active correction, or
- 3. Begin Planning to improve the problem within a reasonable timeframe (within TIP, or 3-5 year program),
- 4. But the "Do Nothing" alternative is <u>NOT</u> acceptable.

How does Conflict Opportunity analysis operate for Roundabouts?

Answer

Identical with an All-Way Stop control intersection <u>except</u> assume:

<u>Delay</u>

- 1. "Yield" not "Stop" Control HCM 4.6 seconds / critical gap
- 2. No "Follow-up" gap each gap acceptance is mutually exclusive
- 3. Right turn "bypass" lanes eliminate right-turns on the specific approach.

Safety with Conflict Opportunities

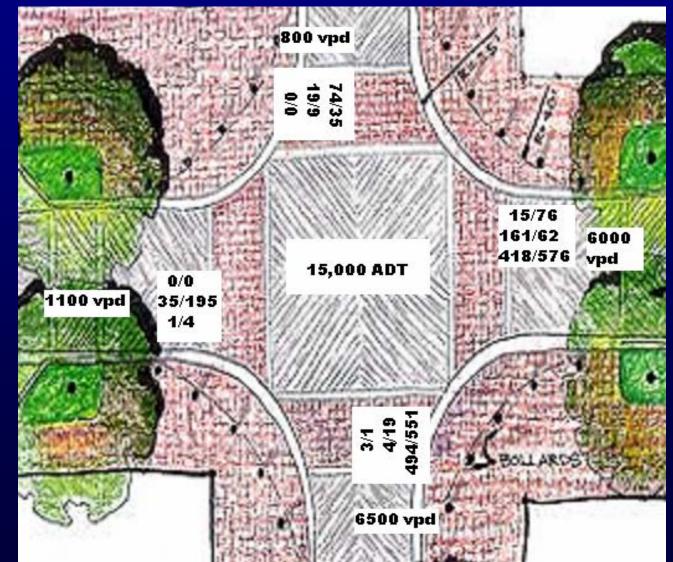
- 1. Frontal Angle conflicts identical to all-way stop except critical gap = "Yield"
- 2. Rear-end conflicts identical to all-way stop except gap = "Yield"
- 3. Sideswipe/Merge conflicts occur "within" single & dual lane roundabout but only on the "approach" to dual lane (similar to multi-lane all-way stop) + distance-based correction to conform to US roundabout accident history.
- 4. Fixed Object/Single Vehicle replaced by "low speed" exposure-based model
- 5. Right "Bypass" lanes eliminate right-turn conflicts on the specific approach.

So, you say you hate learning new computer software

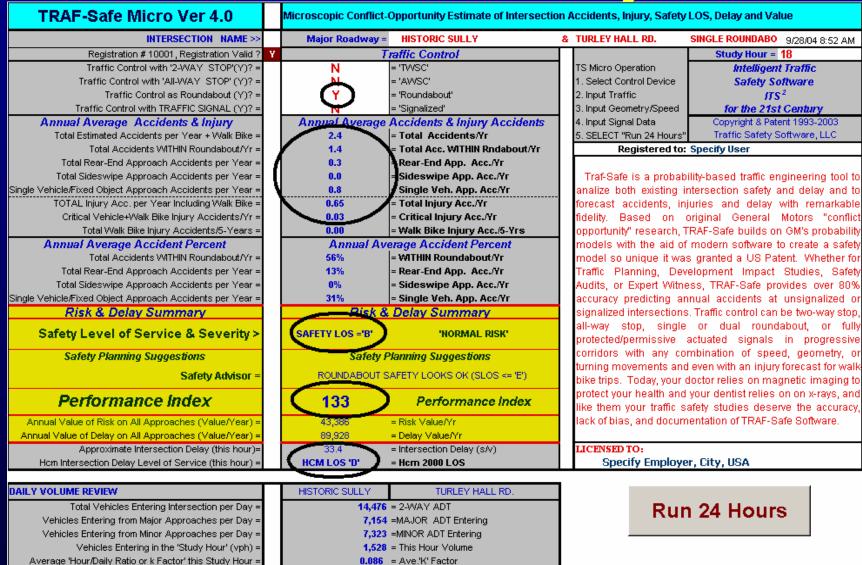


Well, maybe it's not that bad...... Let's take a look

Example Project - Dulles Discovery Rezoning Is a roundabout acceptable ? How does Roundabout performance compare ?



CONFLICT OPPORTUNITY Safety Software



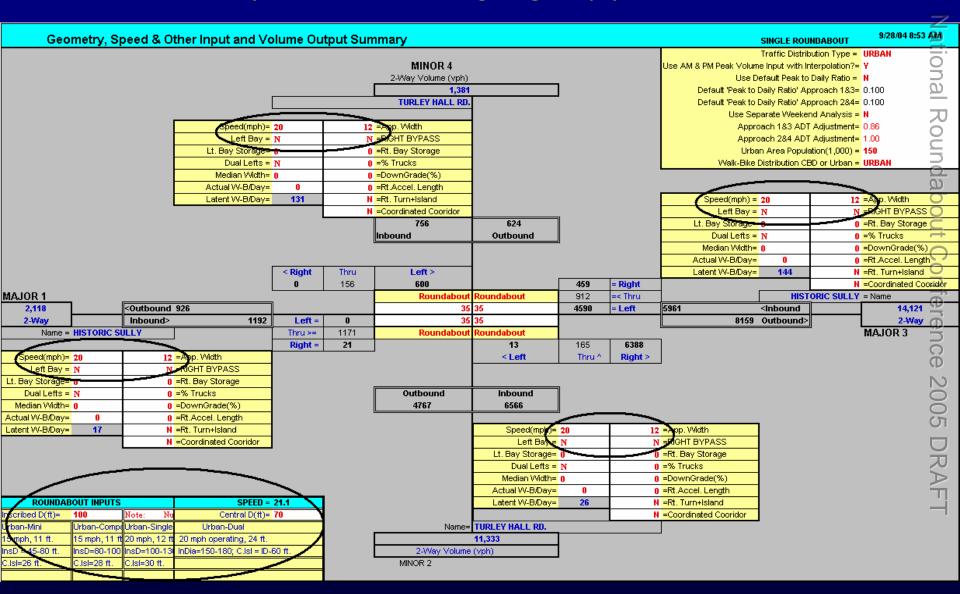
What are the Inputs?

Input AM & PM Volume by Lane

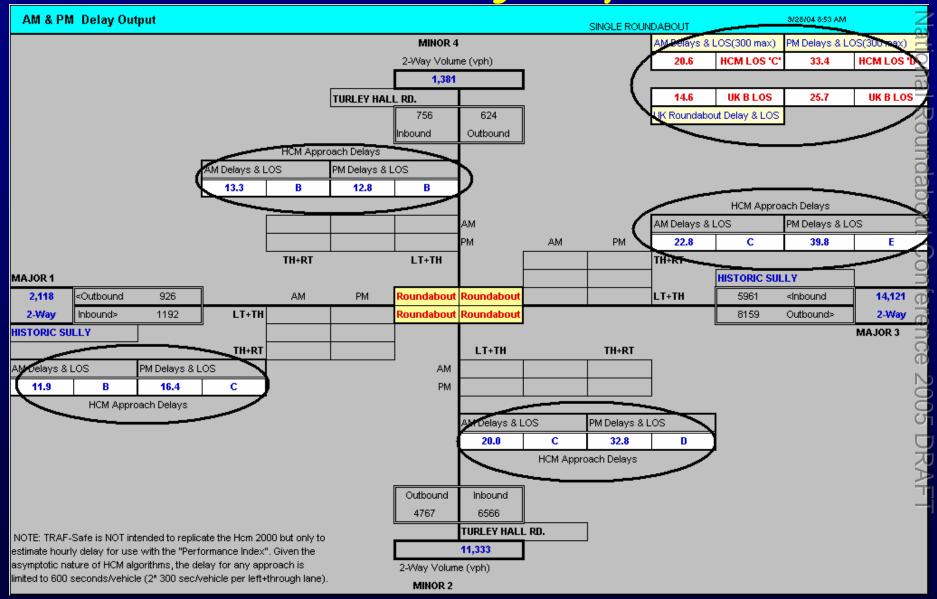
(other hours automatically interpolated)

Estimated I	Hourly Turi	ning Move	ments fron	n Am and/o	r Pm Peak	: Data or In	put Daily	Turning Mo	vements		HISTORIC SL	ILLY	8	TURLEY HAL	L RD.		9/28/04 9:30 AM
	Protected LTs	·Υ			Protected LT:	: Y			Protected LT:	Y			Protected LT	Y			Joj
		Protected RT	N N			Protected RT	N			Protected RT	: N			Protected RT	: N		8
ENDING	Н	ISTORIC SULL	.Υ	Approach 1	TL	JRLEY HALL F	D.	Approach 2	Н	STORIC SULL	.Υ	Approach 3	TL	JRLEY HALL F	RD.	Approach 4	HOURLY
Hour	EB Left	EB Thru	EB Right	Walk-Bike	NB Left	NB Thru	NB Right	Walk-Bike	WB Left	WB Thru	WB Right	Walk-Bike	SB Left	SB Thru	SB Right	Walk-Bike	VOLUME
12-1 AM	0	5	0	0	0	1	38	0	14	2	2	0	2	1	0	0	65
1-2	0	1	0	0	0	2	25	0	8	3	0	0	4	2	0	0	45=
2-3	0	1	0	0	0	1	16	0	6	2	0	0	2	1	0	0	31 🔂
3- 4	0	1	0	0	0	1	20	0	9	4	0	0	3	1	0	0	39
4-5	0	2	0	0	0	1	35	0	19	7	0	0	5	1	0	0	710
5-6	0	7	0	0	0	1	135	0	84	32	3	0	20	5	0	0	288
6-7	0	19	0	0	2	3	311	0	227	87	8	0	47	12	0	0	716—
7-8	0	35	1	0	3	4	494	0	418	161	15	0	74	19	0	0	1224
8-9	0	24	0	0	2	3	390	0	283	109	10	0	58	15	0	0	895
9-10	0	16	0	0	2	2	307	0	192	74	7	0	46	12	0	0	659
10-11	0	11	0	0	1	2	244	0	131	50	5	0	36	9	0	0	490
11-12	0	11	0	0	2	2	278	0	128	49	5	0	42	11	0	0	527—
12-1 PM	0	73	1	0	0	15	435	0	214	23	28	0	28	7	0	0	825 <u></u>
1-2	0	83	2	0	0	15	431	0	246	27	33	0	27	7	0	0	871
2-3	0	90	2	0	0	14	399	0	266	29	35	0	25	7	0	0	866
3-4	0	118	2	0	0	16	451	0	348	37	46	0	29	7	0	0	1054
4-5	0	152	3	0	0	17	498	0	448	48	59	0	32	8	0	0	1265
5-6	0	195	4	0	1	19	551	0	576	62	76	0	35	9	0	0	1528
6-7	0	138	3	0	0	16	455	0	409	44	54	0	29	7	0	0	1154
7-8	0	79	2	0	0	10	303	0	234	25	31	0	19	5	0	0	709
8-9	0	47	1	0	0	7	209	0	139	15	18	0	13	3	0	0	454
9-10	0	34	0	0	0	6	176	0	101	11	13	0	11	3	0	0	356
10-11	0	20	0	0	0	4	118	0	58	6	8	0	8	2	0	0	224
11-12	0	10	0	0	0	2	68	0	29	3	4	0	4	1	0	0	121
	Left Turn		Right Turn		Left Turn		Right Turn		Left Turn		Right Turn			Through	Right Turn		14,476
	0	1171	21		13	165	6388		4590	912	459		600	156	0		TOTAL
DAILY TOTAL	Approach=	1192			Approach=	6566			Approach=	5961			Approach=				
Percent	0%	98%	2%	0	0%	3%	97%	0	77%	15%	8%	0	79%	21%	0%	0	
	MA	JOR APPROA	ACH #1	Walk-Bike	MIN	OR APPROA	CH #2	Walk-Bike	MA	JOR APPROA	ACH #3	Walk-Bike	MA	JOR APPRO	ACH #4	Walk-Bike	

Input Geometry by Approach



Check Delay Output



Check Queuing Output

Left Bay and Thi	rough Queue le	ength (feet)		HISTORIC :	SULLY TURLEY HA	ALL RD.	SINGLE ROUND)ABC 9/28/04 8:5 <mark>2</mark> /АМ
Percentile =	98	70	98	70	98	70	98	70 🔍
	Аррго	oach 1		Approach 2		Approach 3	A	pproach 4
HOUR	Thru Lane Queue	Thru Lane Queue	Thru Lane	Appr. 2 Thru Lane	e Queue Thru Lane	Appr. 3 Thru Lane Queu	e Thru Lane App	pr. 4 Thru Lane Queue
1			0		-		0	0
2	0	0	0	2	0	1	0	0 0
3	0	0	0	1	0	1	0	0 =
4	0	0	0	1	0	1	0	0 0
5	0	0	0	2	0	2	0	1 0
6	0	1	0	8	0	7	0	1 0
7	0	1	0	24	4 0	23	0	2 0
8	0	3	0	59	0	79	0	4 🚍
9	0	2	0	35	5	33	0	3
10	0	1	0	23	3 0	18	0	2
11	0	1	0	17	7	11	0	1 5
12	0	1	0	20	0	11	0	2
13	0	5	0	46	6 0	18	0	1 =
14	0	6	0	46	6 0	22	0	1 💬
15	0	6	0	39	0	24	0	1 0
16	0	9	0	53	0	38	0	1 0
17	0	13	0	/11	0		0	2 100
18	0	{ 20 }	0	100		(153)	0	(2)
19	0	11	0	55	0		0	40
20	0	5	0	24	4 0	20	0	1 07
21	0	3	0	14	4 0	10	0	1
22	0	2	0	11	L O	7	0	1 7
23	0	1	0	7	0	4	0	1 5
24	0	1	0	4		2	0	0
MAX QUEUE (ft) =	0	20	0	10	6 0	153	0	4

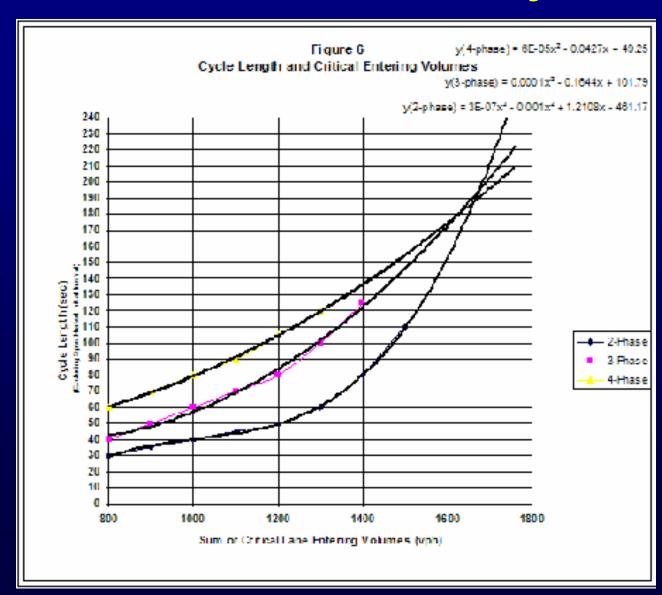
If Signals - Input HCM-based Signal Data

SIGNAL INPUT	MAJOR ROADWAY	MINOR ROADWAY			COMMENTS			9/3/04 12:0	3 PM
Signal Timing Selection 'Traf-Safe' or 'Actual' =	TRAF-SAFE	= Traf-Safe or A					Study Hour =		=
Controller Actuated or Pretimed =	ACTUATED	= Actuated or Pre		_		Red Left (sec)=		1.0	
Traf-Safe Delay Analysis for each hour? =	YES	= Traf-Safe Delay	?		Common All-I	Red Thru (sec)=		2.0	_
Hourly Delay Analysis with Input of Delays ? =	NO	= Input Delay Ana	•				st Time/Phase =		
Number of Phases (2,3, or 4) This Hour =	3	= Phases This Ho					Unit Extension =		
Approximate CYCLE Time(sec) =	53	= TRAF-Safe Cyc	le (sec)	Approach Delay (1-4)				LT MIN IN	IITIAĻ
Effective Through Green Approach 1 & 3 (sec) =	37	= Critical Lt+Th 1 (13			T Approach 1 =		
Effective Through Green Approach 2 & 4 (sec) =	10	= Critical Lt+Th 2		20			T Approach 2 =		Ω
Intersection Control Delay (seconds/vehicle) =	14	= INTERSECTION I	DELAY	13			T Approach 3 =		
				19		L	T Approach 4 =		
Left and Right Turn Characteristics	Protected LT Phase+Bay?		Dual?					THRU MIN	
Left Turns from Approach # 1 =	Y	N	N				U Approach 1 =		
Left Turns from Approach # 2 =	N	Y	N				U Approach 2 =		
Left Turns from Approach # 3 =	Y	N	N	_			U Approach 3 =		Ω
Left Turns from Approach # 4 =	N	Y	N			THR	U Approach 4 =	7.0	
	Protected LT (s)	Sneakers (v/h)							
Left Turns from Approach # 1 =	10	2			l				d
Left Turns from Approach # 2 =	0	1		Timing Summary	Am Peak	Mid-Day	Pm Peak	Off-Pe	ak =
Left Turns from Approach # 3 =	10	2		Begin Time =	6	9	16	20	
Left Turns from Approach # 4 =	0	1		End Time =	9	16	20	6	
				Max Cycle Length =	53	51	53	51	
	Saturation Flow (v/h)	Rt. Turn-on-Red		Phases =	3	3	3	3	
Left and Right Turns from Approach # 1 =	1905	7		Progression Active =	N	N	N	N	
Left and Right Turns from Approach # 2 =	1905	5		Progressive Cycle Length=	180	130	180	120	Ò
Left and Right Turns from Approach #3 =	1905	7							
Left and Right Turns from Approach # 4 =	1905	5		Appr.1 (NEMA 5) Left =		10	10	10	i
				Appr.2 (NEMA 7) Left =		0	0	0	9
Additional Input by Approach	Approach # 1	Approach # 2		Appr.3 (NEMA 1) Left =		10	10	10	
TRAF-Safe/Hcm Arrival Type=	1.4	1.3		Appr.4 (NEMA 3) Left =	0	0	0	0	
Parking per Hour =	0	0							Ţ
Buses per Hour =	0	0		Approach1 (NEMA 2) =		25	27	25	
Approach DownGrade % =	0	0		Approach3 (NEMA 6) =		25	27	25	
Pedestrians per this Hour =	0	0		Overlap Throughs and Lefts =	Υ	Sp	lit Phase 1&3? =	N	
Pedestrian Button + Phase ? =	N	N							
Additional Input by Approach	Approach # 3	Approach # 4		Approach 2 (NEMA 4) =		10	10	10	_
TRAF-Safe/Hcm Arrival Type=	1.4	1.4		Approach 4 (NEMA 8) =		10	10	10	
Parking per Hour =	0	0		Overlap Throughs and Lefts =	N	Sp	lit Phase 2&4? =	N	
Buses per Hour =	0	0							
Approach DownGrade % =	0	0		Max LT Queues		Approach 2 LT	Approach 3 LT	Approach	4 LT
Pedestrians per this Hour =	0	0			48	0	46	0	
Pedestrian Button + Phase ? =	N	N							

Internal Signal Timing - based on ICU Concepts

CM 2000 Cycle & Split Selecto	r			1.00							Study Hour =	18
Movement	Ĵ	-	7	₹	—	t	1	1	^	L	1	ل ا
	EBL	EBT	EBR	₩BL	WBT	WBR	- NBL	■ NBT	■ NBR	SBL	SBT	SBR
1	1								•	•		(A)
Lanes		2	0	1	2	0	0	2	0	0	2	0
SHARED LT Lane ?? (y=1/n=0)	0			0			1			1		
Volume	130	1126	70	130	1126	70	50	232	50	50	232	50
Peak Hour Factor	1	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Pedestrians	0		0	0		0	0		0	0		0
Ped Button (y=1/n=0)	WLK	0	FDNW	WLK	0	FDNW	WLK	0	FDNW	WLK	0	FDNW
Pedestrian Timing Required	0.0	0.0	12.0	0.0	0.0	12.0	0.0	0.0	18.0	0.0	0.0	18.0
Free Right (y=1/n=0)			0			0			0			0
Ideal Flow	1905	1900	1905	1905	1900	1905	1905	1900	1905	1905	1900	1905
Lost Time	0	2	0	0	2	0	0	2	0	0	2	0
Phases & Corridor Cycle Length	Phases=	3.0	Maximu	m Cycle Length =	300						_	
Preliminary Cycle Estimate =	50		SumCriticalVolumes =	869	2-Phase =	50	3-Phase =	50	4-Phase =	60		
												\simeq
Adjusted Volume	130	1126	70	130	1126	70	50	232	50	50	232	50
Volume Combined	130	1196	0	130	1196	0	0	332	0	0	332	0 (1
Volume Separate Left or Right Lane Utilization Factor	130 1,000	1196 0.952	1.000	130 1.000	1196 0.952	0 1.000	0 1,000	282 0.952	1,000	1.000	282 0.952	1,000
Turning Factor Adjust	0.95	0.99	0.85	0.95	0.99	0.85	0.95	0.97	0.85	0.95	0.932	0.85
Saturated Flow Combined	1810	3586	0	1810	3586	0	0	3509	0	0	3509	0
Saturated Flow Separate	1810	3586	0	1810	3586	0	1810	3521	0	1810	3521	0
minimum initial	7.0	12.0	0.00	7.0	12.0	0.00	0.0	7.0	0.00	0.0	7.0	0.00
minimum split	8.0	13.0	0.00	8.0	13.0	0.00	1.0	8.0	0.00	1.0	8.0	0.00
Yellow time	3.00	4.50	0.00	3.00	4.50	0.00	3.00	3.50	0.00	3.00	3.50	0.00
All-red	1.00	2.00	0.00	1.00	2.00	0.00	1.00	2.00	0.00	1.00	2.00	0.00
Extension	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Recall	None	Min	None	None	Min	None	None	None	None	None	None	None
Minimum Green	7	13	0	7	13	0	0	8	0	0	8	0
		0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Ped/Bike Interference Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Ped/Bike Interference Time Hcm LT Adjust Ped/Bike Frequence	1	0.0	0.0%	100.0%	0.0	0.0%	100.0%	0.0	0.0%	100.0%	0.0	0.0%

With Automatic NCHRP/Practical Cycle Length



with Protected, Permitted or Split phase automatically selected for each hour of the day

PROTECTED	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR C
Protected Option Allowed (1=Yes,0=No)	1			1			0			0	-
Reference Time	3.6	16.7	0.0	3.6	16.7	0.0	NA	0.0	0.0	NA	0.0	0.0
Actuated effetive green	10.0	23.2	0.0	10.0	23.2	0.0	3.0	3.5	0.0	3.0	3.5	0.0
Adjusted to Hour Act.Eff.Green	10.0	26.8	0.00	10.0	26.8	0.00	3.0	3.5	0.00	3.0	3.5	0.00
Hourly actuated g/c	0.20	0.54	0.00	0.20	0.54	0.00	0.06	0.07	0.00	0.06	0.07	0.00
												2
		i		ı	1	i		1	:		ı	2
PERMITTED	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Permitted Option Allowed (1=Yes, 0=N	0)	0	Permissive 1&3=	NO	0			1	Permissive 2&4=	YES	1	<u> </u>
Adjusted Saturation A		3586			3586			2348			2348	2
Reference Time A		NA			NA			6.0			6.0	
Adjusted Saturation B		3586			3586			1761			1761	(
Reference Time B		NA			NA			NA			NA	(
Reference Time Lefts	11.6		NA	11.6		NA	0.0		0.0	0.0		0.0
Reference Time		NA			NA			6.0			6.0	ē
Adjusted Reference Time		0.0			0.0			10.0			10.0	
Actuated effetive green	11.6	11.6	NA	11.6	11.6	NA	0.0	10.0	0.00	0.0	10.0	0.00
Adjusted to Hour Act.Eff.Green	11.6	13.4	0.00	11.6	13.4	0.00	0.0	10.0	0.00	0.0	10.0	0.00
Hourly actuated g/c	0.23	0.27	0.00	0.23	0.27	0.00	0.00	0.20	0.00	0.00	0.20	0.00
												1
SPLIT	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Split Timing			SPLIT APP 1&3=	NO					SPLIT APP 2&4=	NO		g
Ref Time Combined Ref Time By Movement	3.6	16.7 16.7		3.6	16.7 16.7		0.0	4.7 4.0		0.0	4.7 4.0	Q
Reference Time	3.0	16.7		3.0	16.7		U.U	4.0		U.U	4.0	l l
Adjusted Reference Time	18.7	18.7		18.7	18.7		10.0	10.0		10.0	10.0	
Actuated effetive green	3.6	18.7	18.7	3.6	18.7	18.7	10.0	10.0	10.0	10.0	10.0	10.0
Adjusted to Hour Act.Eff.Green	3.6	21.6	0.0	3.6	21.6	0.0	10.0	10.0	0.0	10.0	10.0	0.0

Hourly actuated q/c

Check Peak Hour Signal Output

					• • •			,,,,				
Hour= 18											9/28/04 9:52 AM	
Controller Type=	/	HISTORIC SULL'	Y /		URLEY HALL R	D.		HISTORIC SULLY			URLEY HALL RI	D.
ACTUATED	Approach 1 L1	Approach 1 Thr	Approach 1 R	Approach 2 LT	Approach 2 Thr	Approach 2 R	pproach 3 LT	Approach 3 Thr	Approach 3 R	Approach 4 LT	Approach 4 Thr	Approach 4 RT
LT Turn Type	Prot/Perm			Prot/Perm			Prot/Perm			Prot/Perm		
LT Sneakers/Hr	54			54			161			65		
Right-on-Red			2			54						
Ideal Flow	1900	3000	1900	1900	3800	1900	1900	3800	1900	1900	3800	1900
Lane Width Adjust	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Heavy Vehicle %	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%
Heavy Vehicle Adjust	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Grade adjust	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Parking Adjust	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Bus Blockage	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Area Type	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Lane Utilization	1.00	0.95	1.00	1.00	0.95	1.00	1.00	0.95	1.00	1.00	0.95	1.00
Fit	0.95			0.95			0.59			0.29		
Frt			1.00			0.85			0.98			1.00
Ped/Bike Adjust Lt&Rt	1.00		1.00	1.00		1.00	1.00		1.00	1.00		1.00
Sat. Flow Lt Perm	0			0			1069			526		
Sat. Flow Lt Prot	0			0			1810			1810		
Sat Flow Thru		3607			3618			3560			3617	
Sat Flow Rt			0			1619			0			0
Lane Group Flow (vph)	0	199	0	1_	19	497	576	131	0	35	9	0
Walk/Bike Calls per Hour			0			0			0			0
	WLK	Total Time	FDNW	WLK	Total Time	FDNW	WLK	Total Time	FDNW	WLK	Total Time	FDNW
Pedestrian Timing (s)	0.0	0.0	21.0	0.0	0.0	18.0	0.0	0.0	21.0	0.0	0.0	18.0
minimum initial	7.0	12.0	0.0	7.0	7.0	7.0	7.0	12.0	0.0	7.0	7.0	7.0
minimum split	8.0	13.0	0.0	8.0	8.0	8.0	8.0	13.0	0.0	8.0	8.0	0.0
Yellow time	3.0	3.5	0.0	3.0	3.5	3.5	3.0	3.5	0.0	3.0	3.5	0.0
All-red	1.0	1.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0	1.0	1.0	0.0
Extension	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
Recall	None	Min	None	None	None	None	None	Min	None	None	None	None
Minimum Green	7.0	13.0	0.0	7.0	8.0	7.0	7.0	13.0	0.0	7.0	8.0	7.0
Ped/Bike Interference(s)		0.0	0.0		0.0	0.0		0.0	0.0		0.0	0.0
Ped/Bike Frequency		0.00	0.00		0.00	0.00		0.00	0.00		0.00	0.00
Actuated Green (sec)	9.4	16.2	0.0	9.4	12.6	19.1	20.7	16.2	0.0	9.4	12.6	12.6
Actuated Green (g/c)	14%	24%	0%	14%	19%	29%	31%	24%	0%	14%	19%	19%
		074	4000		000	4000			4000	***		4000
Lane group capacity	0.00	874 0.06	1600 0.00	54 0.00	683 0.01	1603 0.31	980 0.32	863	1600 0.00	418 0.02	683 0.00	1600
v/s Ratio V/C Ratio	0.00	0.06	0.00	0.00	0.01	0.31	0.32	0.04 0.15	0.00	0.02	0.00	0.00
Uniform Delay D1	0.00	20.3	0.00	0.02	22.1	0.0	4.3	19.9	0.00	9.7	22.1	0.00
Progression factor	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
Incremental delay D2	0.0	0.6	0.0	0.0	0.1	0.5	2.6	0.4	0.0	0.4	0.0	0.0
Delay (sec)	0.0	20.9	0.0	0.0	22.2	0.5	6.9	20.3	0.0	10.0	22.1	0.0
Level of Service	A	С		А	С		А	С		В	С	
Approach Delay (sec)		21			21			8			12	
Approach LOS		С			С			A			В	
				1								
HCM Control Delay	15	Inters	ection LOS =									
Cycle length Used	67		B HCM LOS.		l							

Check Hourly Signal Output Throughout Day Cycle, Phase (thru+turn) & Splits

Daily Timi	ng Summary			MAJOR ROAD	WAY	MINOR RO	ADWAY		COMME	NTS	9/3/04 12:03 PM	18
	1 & 3 Phasing	App. 1 Left	App. 1 Thru	App. 3 Left	App. 3 Thru	2 & 4 Phasing	App. 2 Left	App. 2 Thru	App. 4 Left	App. 4 Thru	Cycle	
AM												DELAY
5-6Am Hour 6	Prot	10	25	10	25	LtPerm	0	10	0	10	51	10
6-7 Hour 7	Prot	10	25	10	25	LtPerm	0	10	0	10	51	11
7-8 Hour 8	Prot	10	27	10	27	LtPerm	0	10	0	10	53	14
8-9 Hour 9	Prot	10	25	10	25	LtPerm	0	10	0	10	51	12
Mid-Day												
9-10 Hour 10	Prot	10	25	10	25	LtPerm	0	10	0	10	51	11
10-11 Hour 11	Prot	10	25	10	25	LtPerm	0	10	0	10	51	10
11-12 Hour 12	Prot	10	25	10	25	LtPerm	0	10	0	10	51	11
12-1 Hour 13	Prot	10	25	10	25	LtPerm	0	10	0	10	51	12
1-2 Hour 14	Prot	10	25	10	25	LtPerm	0	10	0	10	51	12
2-3 Hour 15	Prot	10	25	10	25	LtPerm	0	10	0	10	51	12
3-4 Hour 16	Prot	10	25	10	25	LtPerm	0	10	0	10	51	12
PM												
4-5 Hour 17	Prot	10	26	10	26	LtPerm	0	10	0	10	52	13
5-6 Hour 18	Prot	10	27	10	27	LtPerm	0	10	0	10	53	14
6-7 Hour 19	Prot	10	25	10	25	LtPerm	0	10	0	10	51	12
Off-Peak												
7-8 Hour 20	Prot	10	25	10	25	LtPerm	0	10	0	10	51	11
8-9 Hour 21	Prot	10	25	10	25	LtPerm	0	10	0	10	51	10
9-10 Hour 22	Prot	10	25	10	25	LtPerm	0	10	0	10	51	10
10-11 Hour 23	Prot	10	25	10	25	LtPerm	0	10	0	10	51	9
11-12 Hour 24	Prot	10	25	10	25	LtPerm	0	10	0	10	51	9
12-1 Hour 1	Prot	10	25	10	25	LtPerm	0	10	0	10	51	9
1-2 Hour 2	Prot	10	25	10	25	LtPerm	0	10	0	10	51	9
2-3 Hour 3	Prot	10	25	10	25	LtPerm	0	10	0	10	51	9
3-4 Hour 4	Prot	10	25	10	25	LtPerm	0	10	0	10	51	9
4-5 Hour 5	Prot	10	25	10	25	LtPerm	0	10	0	10	51	9

Check Hourly /Annual Safety Output

			1041	• • • • • • • • • • • • • • • • • • • •							
Hourly Sum	mary of Anni	ual Data						HISTORIC SULL	Υ	8	TURLEY HA
	Estimated	Delay/Year			Annı	ual Vehicle	-Only Eve	nts			
	Major Road	Minor Road									
	Appr. 183	Appr. 284		Forecast Accident Events Forecast							
HOUR	Hours/Year	Hours/Year	Total/Yr	WITH-IN	Rear-End	Sideswipe	Fixed Obj/Sir	HOUR	TOTAL/Yr	Critical/5-Yrs	HOUR
1	41	42	0.00	0.00	0.00	0.00	0.00	1	0.00	0.00	1
2	23	24	0.00	0.00	0.00	0.00	0.00	2	0.00	0.00	2
3	15	15	0.00	0.00	0.00	0.00	0.00	3	0.00	0.00	3
4	19	19	0.00	0.00	0.00	0.00	0.00	4	0.00	0.00	4
5	34	34	0.00	0.00	0.00	0.00	0.00	5	0.00	0.00	5
6	137	140	0.02	0.01	0.00	0.00	0.02	6	0.00	0.00	6
7	387	396	0.10	0.05	0.01	0.00	0.04	7	0.02	0.00	7 🤦
8	987	1,010	0.26	0.14	0.06	0.00	0.06	8	0.08	0.00	8
9	787	805	0.15	0.08	0.02	0.00	0.05	9	0.04	0.00	9
10	533	545	0.09	0.04	0.01	0.00	0.03	10	0.02	0.00	10
11	389	399	0.05	0.03	0.00	0.00	0.03	11	0.01	0.00	11
12	456	466	0.06	0.03	0.00	0.00	0.03	12	0.01	0.00	12
13	693	709	0.11	0.06	0.01	0.00	0.04	13	0.03	0.00	13
14	688	705	0.13	0.07	0.01	0.00	0.05	14	0.03	0.00	14
15	615	630	0.13	0.08	0.01	0.00	0.05	15	0.03	0.00	15
16	800	819	0.19	0.12	0.02	0.00	0.06	16	0.05	0.00	16
17	1,106	1,132	0.28	0.17	0.04	0.00	0.07	17	0.08	0.00	17 (
18	2,083	2,132	0.41	0.25	0.08	0.00	0.08	18	0.13	0.01	18
19	926	947	0.23	0.14	0.03	0.00	0.06	19	0.07	0.00	19
20	435	446	0.10	0.05	0.01	0.00	0.04	20	0.02	0.00	20
21	266	272	0.05	0.02	0.00	0.00	0.02	21	0.01	0.00	21
22	216	221	0.03	0.01	0.00	0.00	0.02	22	0.01	0.00	22
23	139	142	0.02	0.01	0.00	0.00	0.01	23	0.00	0.00	23
24	77	70	0.01	0.00	0.00	0.00	0.01	24	0.00	0.00	24
TOTAL/Yr	11,851	12,130	2.4	1.37	0.32	0.00	0.76		0.65	0.03	
	Delay/Year	Delay/Year	Accidents/Yr	WITH-IN	Rear-End	Sideswipe	Fixed Obj/Sir		Injury Acc./Yr	Critical/5-Yrs	
					iggl)				Fatal/5-Yrs		
									$\overline{}$	Note: The rate-	
			lacro) Accide		nate		TRAF Safe		is of Service		
MDOT-I	Round Acc/Yr =	2.5		an Std.Dev.=		S	afety Los 'A' <	0.43		ety LOS Criter	
			Small Urb	an Std.Dev.=		1 1	afety Los 'B' <	0.87	0.65	Traf-Safe Injury	Acc.+Peds/\

1.30

1.74

2.17

PLANNING LIMIT OF ACCEPTABLE RISK
DESIGN LIMIT OF ACCEPTABLE RISK

POTENTIALLY HAZARDOUS DESIGN

MDOT-Roundabout Inj-Acc./Yr =

UK Roundabout Inj-Acc./Yr=

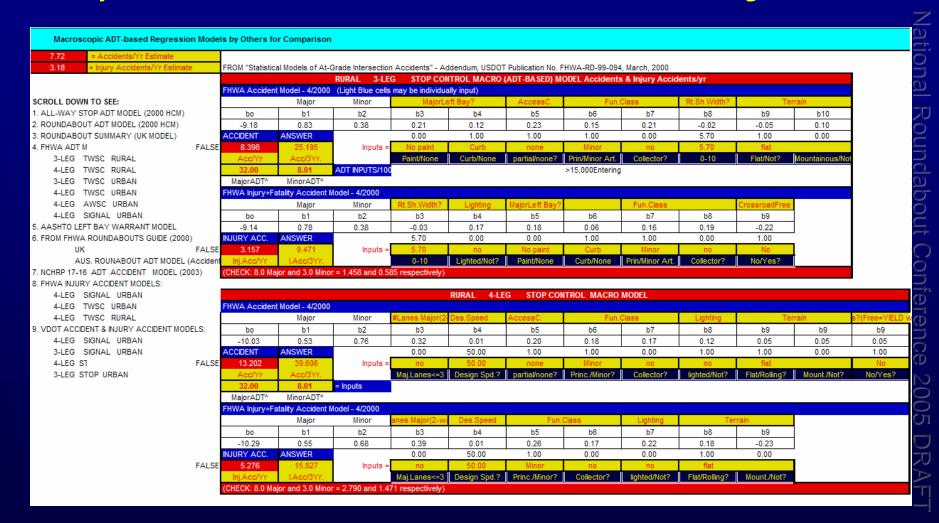
Alternative ADT-Based Injury Accidents/Yr Estimate

0.6

Large Urban Std.Dev.=

Small Urban Std.Dev.=

Compare to FHWA & British Macro-Safety Models



Recognize that: Regression Accident Model Accuracy
< 35 % Accurate

DELAY RESULTS ??

	HCS-based Delay	Conflict Software Delay \geq
TWSC		atic
Am	8.1	Connict Software Delay National 6.3
Pm	14.9	
<u>AWSC</u>		Roundabout F
Am/Pm LOS	В	
<u>Signal</u>		Conference 11.9 15.0
Am	8.9	11.9 Pro
Pm	8.8	
Roundabout		2005 i
Am	9.5	20.6 ¹
Pm	10.3	33.4 1 1. Very conservative lower bound critical gap

Within the 30% error margin when comparing HCS results to actual field delay

SAFETY RESULTS ??

Accidents - Injuries - Lifetime Risk

	TWSC	AWSC	<u>Signal</u>	Roundabou
<u>Accidents</u>	0.5	1.5	1.4	2.4
Injury Acc.	0.12	0.15	0.42	0.65
Safety LOS	B	B	A	B
Performance Index (Safety+Delay Value)	<i>58</i>	741	94	133

Conclusions?

- 1. AWSC Unacceptable delay = LOS "F"
- 2. Signal may not warrant (15,000 ADT) annual cost
- 3. TWSC and Roundabout Safety LOS = B = OK
- 4. Thus developer may select TWSC or Roundabout

(Both are acceptable and only have slight differences)

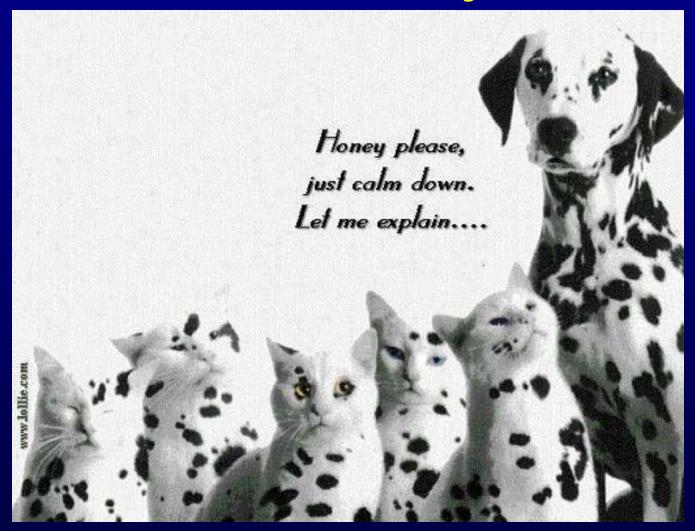
www.Traf-Safe.com

If Had Walk/Bike Mode

Injury Accident Estimation can be included

WALK/BIKE MODULE	COMMENTS	9/3/04 12:03 PM
	MAJOR ROADWAY	MINOR ROADWAY
Walk/Bike Mode Total Injury Events/5-Yrs =	0.00	
Walk/Bike Mode Critical Injury Events/5-Yrs =	0.00	
APPROACH 1 & 2	Major # 1	Minor # 2
Total WALK/BIKE Distance on this Approach (ft) =	72	48
Total WALK/BIKE Mode per Day (this approach) =	0	0
Percent Young Crossing (age 2-14)/Day =	0	0
Percent Typical Crossing (age 15-55)/ Day =	95	95
Percent Elder Crossing (ages > 55)/ Day =	5	5
Percent Crossing Handicap Peds/ Day =	0	0
Effective Total Crossings Walk+Bike/Day =	0	0
AADT This Approach =	30,790	9,218
WALK/BIKE Injury Events/5-Yrs this approach =	0.000	0.000
Percent Critical Injuries =	43%	24%
Estimated Critical Events/5-Yrs =	0.000	0.000
APPROACH 3 & 4	Major # 3	Minor # 4
Total WALK/BIKE Distance on this Approach (ft) =	72	48
Total WALK/BIKE Mode per Day (this approach) =	0	0
Percent Young Crossing (age 2-14)/Day =	0	0
Percent Typical Crossing (age 15-55)/ Day =	95	95
Percent Elder Crossing (ages > 55)/ Day =	5	5
Percent Crossing Handicap Peds/ Day =	0	0
Effective Total Crossings Walk+Bike/Day =	0	0
AADT This Approach =	30,790	9,218
WALK/BIKE Injury Events/5-Yrs this approach =	0.000	0.000
Percent Critical Injuries =	43%	24%
Estimated Critical Events/5-Yrs =	0.000	0.000

But let's remember....it's just software



Only <u>qualified engineering judgment</u> can define what's safe & what's not....but software can help defend your decision and explain why.